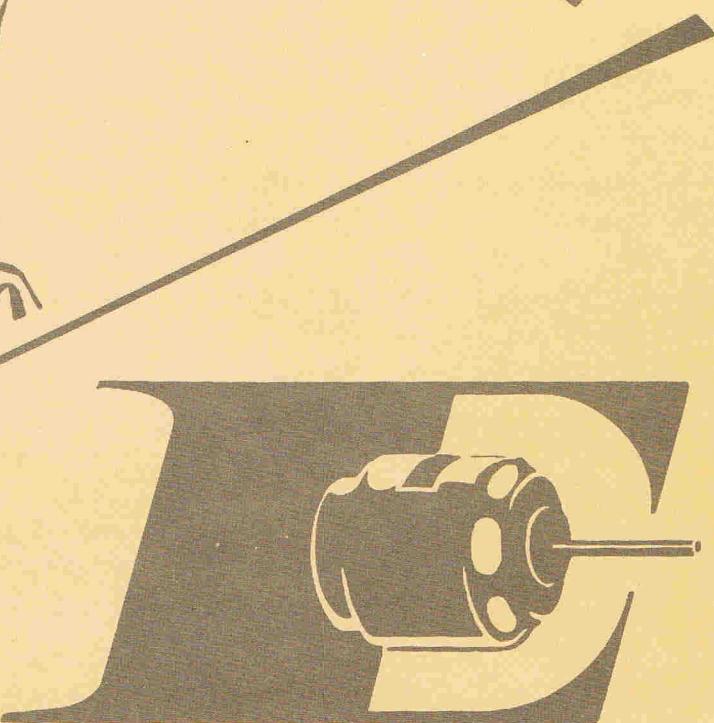


# SYNCHRONOUS MOTORS

HYSTERESIS MOTORS AND SALIENT POLE INDUCTION MOTORS

FRACTIONAL



HORSEPOWER

**DILLINCO**



# Electric Indicator Company

This catalog provides complete electrical and physical configurations available on 309 Elinco Synchronous Motors. These units have been selected as standards with wide applications. For example, dual speed motors shown have mostly equal torque at both speeds. Elinco has several hundred special designs available. For instance, it might be desired to have more torque at one speed than the other. In other words, one might want 55 in. oz. at 1,200 RPM and only 15 in. oz. at 3,600 RPM. Also available are derated motors where a low temperature rise is desired, or high torque motors where temperature rise or intermittent duty is not critical.

Elinco's engineering staff has worked for 40 years with leading engineers to custom tailor motors to their needs, whether this be special electrical or mechanical design. We have solved many tough fabrication and assembly problems and we can solve problems of heat, vacuum, humidity, shock, vibration and weight.

**Delivery:** A large inventory of standard parts is maintained, but the great variety of units offered precludes carrying an inventory of complete motors. Standard catalog items require a reasonable time for assembly and testing therefore units of special design will take proportionately longer.

**Prices:** Elinco motors are custom crafted and the prices depend on quantity ordered. Standard price break quantities are (1-9), (10-24), (25-49), (50-99), (100-249), etc. Elinco will supply quotes to your electrical and mechanical specifications.

Motors thus marked (\*) indicate special internal construction to achieve higher torques in a small package. The prices on these run about 15% more than the preceding motors. This is pointed out so that the higher torque motor will not be selected if the torque is not required, since a premium price must be paid for the higher torque when required.

## **GUARANTEES:** The general guarantees recommended by N.E.M.A., by which this Company has always abided, are as follows:

"The manufacturer agrees to correct, and shall have the right to correct, by repair or replacement, at his own expense, at his option, F.O.B., his works, any defects in said apparatus which may develop under normal and proper use within twelve months after date of shipment, when inspection proves the claim; providing the purchaser gives the manufacturer immediate written notice of such defects, and provided further that during said period apparatus is properly cared for, operated under normal conditions and with competent supervision. The correction of such defects by repair or replacement by the manufacturer shall constitute a fulfillment of all his obligations to the purchaser."

"The manufacturer shall not be responsible for any damage resulting from improper storage or handling prior to placing the apparatus in service, and the manufacturer shall not assume any expense or liability for repairs made outside his works, without his written consent."

"The manufacturer shall not be liable for consequential damage in case of any failure to meet the conditions of any guarantee."

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OMIT "H" IN ABOVE FRAME TYPES FOR SALIENT POLE INDUCTION  
SYNCHRONOUS MOTOR (PAGE 18 & 19)

# THEORY OF THE HYSTERESIS MOTOR

The hysteresis synchronous motor is so named because it utilizes the phenomenon of hysteresis to produce mechanical torque. In its simplest form, the rotor of a hysteresis motor is a smooth cylindrical tube of high hysteresis loss permanent magnet material without windings or slots. It is placed within a slotted stator carrying distributed windings designed to produce, as nearly as possible, a sinusoidal space dis-

tribution of flux. In single phase motors, the stator windings usually are the permanent-split-capacitor type. The capacitor value is selected to result in approximately balanced 2 phase conditions within the motor windings. The stator then produces a rotating field, approximately constant in space wave form and rotating at synchronous speed.

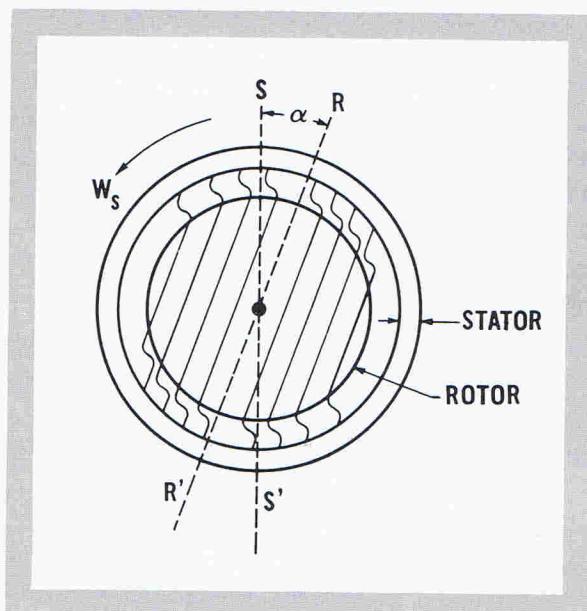


figure 1

The motor therefore develops constant torque right up to synchronous speed, as shown in the ideal speed torque, Figure 2. This feature is one of the advantages of the hysteresis motor in contrast to a reluctance motor which must snap its load into synchronism from the induction motor torque speed characteristic. Hysteresis motors can synchronize any load they can accelerate, regardless of the inertia. After reaching synchronism the motors continue to run at synchronous speed and adjust their torque angle to develop torques required by the loads.

There are deviations from the ideal speed torque curves for several reasons. In a single phase capacitor motor, a true two phase condition occurs only at one load point. It is not always possible to obtain a true sinusoidal winding distribution tooth pulsation loss in the rotor etc., so that speed torque curves A and B can be obtained. Therefore there is some flexibility in design possible to obtain curves A or B; curve A, when starting torque is not required; curve B, when a high starting torque is required.

Instantaneous magnetic conditions in the air gap are indicated in Figure 1 for a 2 pole stator. The axis SS' of the stator m.m.f. wave revolves at synchronous speed, because of hysteresis the magnetization of the rotor lags behind the inducing m.m.f. wave, and therefore the axis RR' of the rotor flux wave lags behind the axis of the stator m.m.f. wave by the hysteresis lag angle " $\alpha$ ". If the rotor is stationary, starting torque is produced proportional to the product of the fundamental components of the stator m.m.f. and rotor flux and the sine of the torque angle " $\alpha$ ". The rotor then accelerates if the counter torque of the load is less than the developed torque of the motor. When the rotor is turning at less than synchronous speed, each particle of the rotor is subjected to a repetitive hysteresis cycle at slip frequency. While the rotor is accelerating, the lag angle " $\alpha$ " remains constant if the flux is constant, since the angle " $\alpha$ " depends merely on the hysteresis loop of the rotor and is independent of the rate at which the loop is traversed.

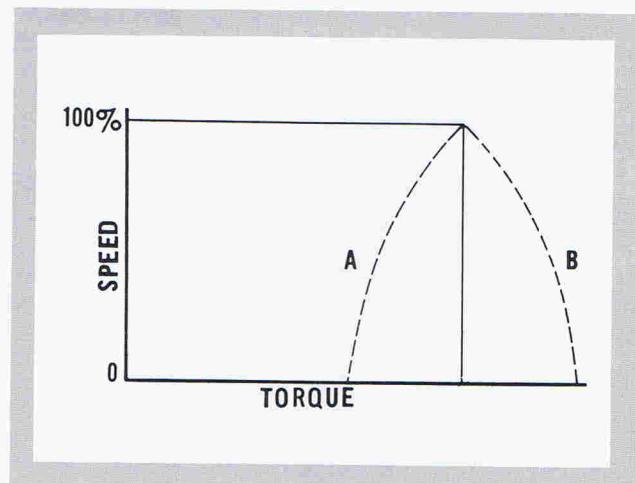
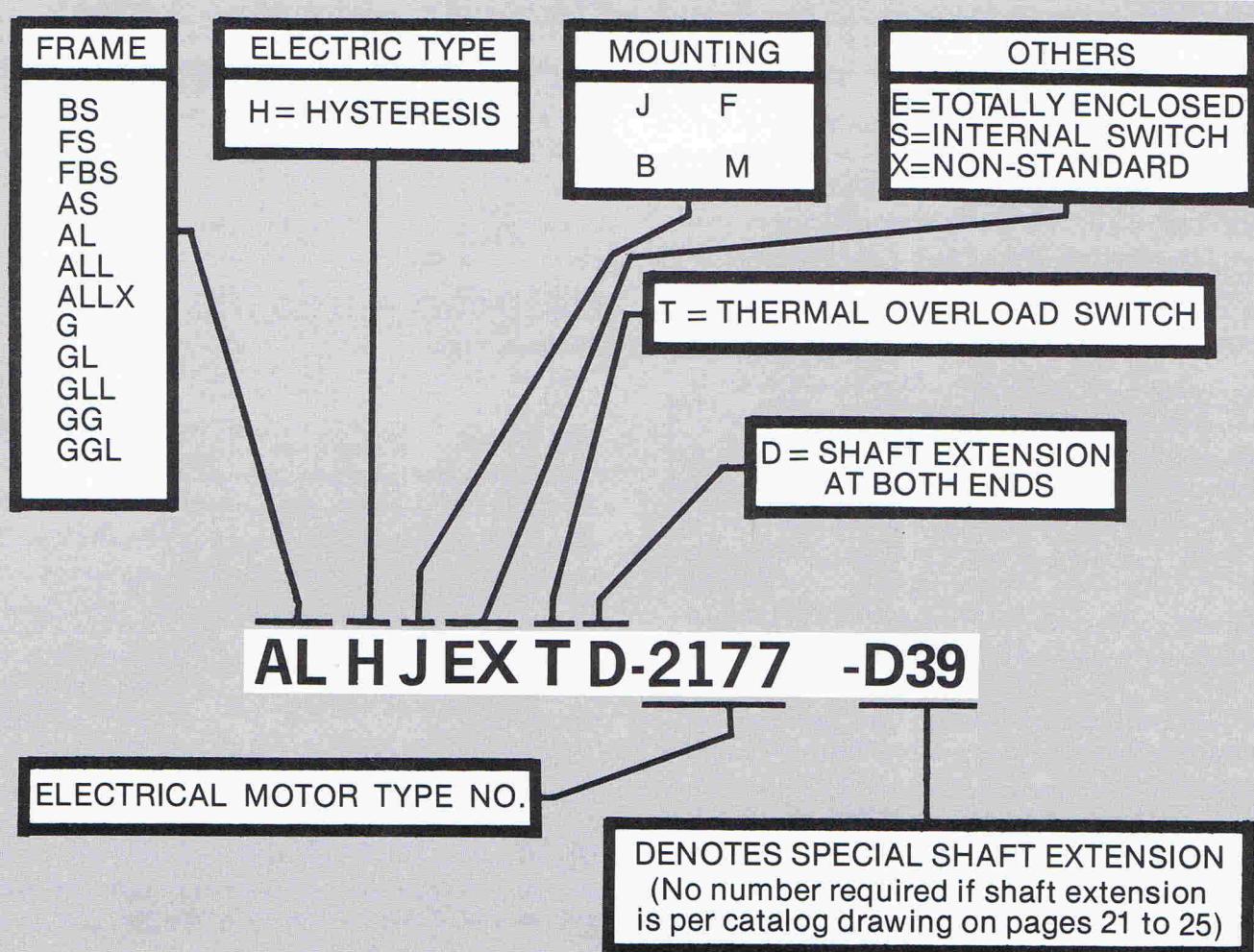


figure 2

# ELINCO DESIGNATION SYSTEM



**SHAFTS** are made of stainless steel to dimensions shown on the frame outline drawings in the catalog. Other dimensions or materials and special features such as flats, slots, splines, threads, double extensions, etc. can be furnished if requested.

**BALL BEARINGS** with seals and/or shields are lubricated for the life of the bearings. Chrome or stainless steel material is used depending on the requirements.

**FRAME MATERIAL** is cast aluminum. A blue-grey mottletone baked enamel is furnished on all non-mounting exterior surfaces. Other colors can be provided if requested.

**VENTILATION**, utilizing an internal fan, is provided on all A and G frames. These frames can also be supplied as totally enclosed units with a reduced horsepower rating. The BS, FS, BSJ, and FBS frame are normally supplied totally enclosed.

**SPECIAL TREATMENT** can be provided to meet extreme conditions of humidity, fungus environment, vibration, shock, high and low temperature and other requirements of military specifications.

**SPECIAL MOUNTING** or mechanical configuration can be supplied when requested. Various units from this and other Elinco catalogs can be combined into a single frame to meet special electrical requirements.

# ELECTRICAL CHARACTERISTICS FOR HYSTERESIS AND SALIENT POLE SYNCHRONOUS MOTORS

## VOLTAGE:

All frames, both in hysteresis and salient pole can be wound for voltages up to 440 volts.

## SPEED:

The synchronous speed for the hysteresis and salient pole motors is determined by the formula:

$$\text{Synchronous RPM} = \frac{120 \times \text{Line Frequency}}{\text{Number of Poles}}$$

The following speeds are available by frames:

Hysteresis Motors:	50 Hertz RPM	60 Hertz RPM	400 Hertz RPM	Poles
"BS", "FS" or "FBS"	1000	1200	8000	6
	1500	1800	12000	4
	3000	3600	24000	2
"AS" "AL" "G" "GL"	500	600	4000	12
	750	900	6000	8
	1000	1200	8000	6
	1500	1800	12000	4
Salient Pole Motors:  "BS", "FS" or "FBS"	3000	3600	24000	2
	60 Hertz RPM		Poles	
	1800		4	
	3600		2	
	1200		6	
"AS", "AL" "G" "GL"	1800		4	
	3600		2	

### NOTE:

Synchronous speeds will vary directly with frequency. Dual speed hysteresis 60 or 400 hertz motors can be supplied in any combination of the above single speeds. Three and five speed motors are listed on pages 14 and 15.

## FREQUENCY:

Hysteresis synchronous motors are available or can be developed, in each frame, in any desired frequency from 15 hertz to 1200 hertz. Salient pole synchronous motors are available or can be developed, in each frame, in any desired frequency from 15 hertz to 240 hertz.

## WINDINGS:

Motors can be wound for one, two or three phase operation, with class (H) insulation and other special features. Many units for special application are not shown in the catalog. If the motor you require is not shown, send us your specifications.

## INSULATION:

The following classes of insulation are safe for the following continuous duty at the listed temperatures. The listed temperatures are the absolute value of temperature which consists of the temperature rise of the motor and the ambient temperature.

Class A	105°C	221°F
Class F	155°C	311°F
Class H	180°C	356°F

## HORSEPOWER RATINGS AT RATED TORQUE:

### Hysteresis Motor:

"BS" or "FS" frame	1/500 to 1/200 HP
"FBS" frame	1/250 to 1/100 HP
"AS" frame	1/300 to 1/50 HP
"AL" frame	1/250 to 1/25 HP
"G" frame	1/75 to 1/10 HP
"GL" frame	1/50 to 1/6 HP

### Salient Pole Motors:

"BS" or "FS" frame	1/500 to 1/250 HP
"FBS" frame	1/250 to 1/125 HP
"AS" frame	1/300 to 1/75 HP
"AL" frame	1/250 to 1/50 HP
"G" frame	1/75 to 1/15 HP
"GL" frame	1/50 to 1/10 HP

## DEFINITION OF CATALOGUE TERMS

All motors will meet rated torque at rated voltage, frequency and capacitor. All other data given is nominal.

### Starting Torque

The starting torque of a motor is the torque which the motor will develop at rest at any angular position of the rotor.

### Pull Out Torque

The pull out torque is the maximum torque which the motor will develop at synchronous speed.

### Pull In Torque

The pull in torque is the maximum torque under which the motor will pull into synchronous speed as the rotor approaches synchronous speed.

### Pull Up Torque

The pull up torque is the minimum torque developed by the motor during the period of acceleration from zero speed to pull in torque.

# SYNCHRONOUS MOTORS

## CHARACTERISTICS OF THE HYSTERESIS TYPE

### NOISE AND VIBRATION

The Hysteresis Synchronous motor consists of a wound stator and a rotor of uniform high permeable material. Having a smooth rotor of homogenous material, the noise and vibration produced is inherently low. Since there are no pole faces or saliences, the magnetic path is of constant permeability, thus eliminating the magnetic pulsations which are the major cause of noise in the salient pole type.

### TORQUE

The torque of the motor is uniform due to the homogenous rotor and constant permeability. There is no variation in torque throughout a revolution. The availability of new materials and designs have increased the torque and horsepower values into the one horsepower range.

### SPEED

The speed of the Hysteresis Synchronous motor is determined by poles and line frequency as given in the formula on page 4. This speed is constant regardless of load variations within the rating of the motor. With a variation of load, however, the rotor will assume a new load angle dependent on the load variation.

Where large load variations or fluctuation of line voltage occur, the stabilized Hysteresis motor can be used to reduce hunting. This motor type is described on page 16.

The rotor of the Hysteresis motor, not requiring pole saliences allows for the design of low speed motors as well as multi-speed motors using the same rotor. Five speed motors and low speeds of 600 rpm, are standard items. Variations to the number of speeds and lower speeds are available in special designs.

The two most popular fractional horsepower Synchronous motors used in precision and semi-precision design are the Hysteresis and the Salient pole or Reluctance types.

### LOAD INERTIA

The Hysteresis Synchronous motor is capable of synchronizing high inertia loads, being unaffected by load inertia, it need only be powerful enough to drive the frictional component of load. The Hysteresis Synchronous motor can pull into synchronism high inertia loads that would require a salient pole motor several times its horsepower rating.

### STARTING TORQUE

In the Hysteresis Synchronous motor, the starting torque is constant throughout 360° of rotor position. Where uniform starting torque or constant tension is required, Hysteresis Synchronous motors, due to the absence of cogging, have been used successfully as torque motors.

### PHASING

The rotor of the Hysteresis Synchronous motor, having no pole saliences, will lock in phase in any of the 360° of rotor rotation.

In applications where definite phasing is required, the polarized Hysteresis motor is recommended. This type of motor has one-half the "lock-in" points of the salient pole Induction motor. The description of this motor type is on page 16.

### SUMMARY

The Hysteresis Synchronous motor characteristics are:

- Low noise and vibration
- Constant speed regardless of load and voltage variation within motor rating
- Capability of synchronizing high inertia loads
- Uniform starting torque
- Can be wound for lower speed and greater number of poles than is practical with salient pole Induction type motors
- Can be provided as multi-speed motor
- Will lock in at any position with respect to line voltage

### MOTOR WEIGHT AND ROTOR MOMENT OF INERTIA

FRAME	WEIGHT (Approx.)	MOMENT OF INERTIA (Oz. In. <sup>2</sup> )
BS-FS-BSJ	19 Oz.	0.6 to 0.7
FBS	30 Oz.	1.1 to 1.2
AS	3 $\frac{1}{4}$ Lbs.	2.4 to 3.8
AL	4 $\frac{1}{2}$ Lbs.	3.0 to 4.7
ALL	5 Lbs.	4.6 to 7.1
ALLX	6 Lbs.	5.3 to 8.4
G	7 $\frac{1}{4}$ Lbs.	13.2 to 18.6
GL	10 $\frac{1}{2}$ Lbs.	16.4 to 31.4
GG	13 $\frac{1}{2}$ Lbs.	26.4 to 37.2

# SINGLE SPEED MOTORS

SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	830	1200	1/500	14	1.6	2.0	1.8	1.8	1	220	figs. 1, 2, 3 page 21
BS	698	1800	1/350	16	1.6	2.0	1.4	1.8	1	220	
BS	1217	3600	1/200	16	1.4	1.6	1.6	1.5	2	220	
FBS	831	1200	1/250	27	3.2	4.0	4.0	3.6	2	220	
FBS	583	1800	1/125	30	4.4	6.0	4.8	5.4	2	220	
FBS	586	3600	1/100	27	2.8	4.3	3.3	3.6	2	220	
AS	2474	600	1/300	40	5.6	6.0	9.0	5.8	2	220	
AS	2297	900	1/250	30	4.5	6.2	11.2	5.8	2	330	
AS	2476	1200	1/75	40	11.2	13.5	15.0	13.0	2	330	
AS	2464	1800	1/50	50	11.0	12.8	16.0	12.1	3	330	
AS	762	3600	1/50	41	5.6	7.5	8.5	7.0	3	220	
AL	2475	600	1/200	45	8.0	11.0	12.2	10.1	3	220	figs. 1-4 pages 22 & 23
AL	2462	900	1/125	48	9.0	10.1	21.5	9.7	3	220	
AL	2457	1200	1/75	40	11.2	13.7	16.0	13.1	2	330	
AL	724	1800	1/45	52	12.0	16.0	14.0	14.0	3	220	
AL	693	3600	1/30	60	9.6	10.7	12.0	9.9	5	220	
ALL	1493*	600	1/150	60	11.2	15.0	11.5	14.0	5	220	
ALL	1683*	900	1/50	93	22.4	27.2	32.0	24.8	5	330	
ALL	2573	1800	1/25	78	22.4	29.0	26.0	28.0	3	330	
ALL	2307	3600	1/20	81	14.0	19.2	19.2	18.4	5	330	
G	353	600	1/150	57	11.2	13.7	20.0	12.0	4	330	
G	2472	900	1/50	76	22.5	26.0	35.0	24.5	3	330	figs. 1-4 pages 24 & 25
G	2502	1200	1/30	82	28.0	32.0	38.0	30.0	3	330	
G	1586	1800	1/15	102	37.0	46.5	48.0	43.0	6	330	
G	2440	3600	1/12	157	23.3	30.0	36.5	28.8	6	330	
GL	2486	600	1/60	94	28.0	32.0	33.6	30.4	4	330	
GL	2506*	600	1/45	111	37.0	44.0	56.6	41.6	4	440	
GL	1613	900	1/25	115	45.0	59.0	64.0	54.0	5	330	
GL	2441*	900	1/20	115	60.0	70.5	65.6	67.3	4	440	
GL	2221*	1200	1/10	170	84.0	110.0	101.0	105.8	8	330	
GL	2428	1800	1/10	129	56.0	65.8	59.2	59.5	6	330	
GL	1128	1800	1/8	172	70.0	86.0	86.0	73.0	10	330	
GL	1921*	1800	1/5	277	112.0	130.0	126.0	120.0	12	330	
GL	2137	3600	1/6	250	44.0	54.5	70.0	48.0	10	330	

\*See inside front cover

# SINGLE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
AL	2110	70	3600	1/30	55	9.0	12.2	12.2	11.7	7	220	figs pages 22 & 23
ALL	2092	230	1800	1/40	65	14.0	20.8	35.2	17.6	5	330	
ALL	2173	220	1800	1/25	78	22.5	27.0	32.0	26.0	4	330	
GL	2011*	230	1800	1/10	190	56.0	72.0	56.0	64.0	3	550	
GL	1046	230	3600	1/7	207	40.0	48.0	72.8	44.0	4	550	

\*See inside front cover

# TWO PHASE, ODD FREQUENCY, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	Hertz	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
FBS	1121	28	450	22 1/2	1/1500	16	1.5	3.5	1.5	1.8	fig. 4 page 21
AL	1047	115	7200	240	1/25	55	5.6	6.9	12.0	6.6	figs. 1-4 pages 22 & 23

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# SINGLE SPEED MOTORS

# TWO PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
BS	1877	22	1800	1/250	26	2.2	2.8	2.6	2.6	figs. 1, 2, 3 page 21
AS	2493	115	1200	1/75	48	1.2	12.5	19.2	12.1	
AL	425	55	900	1/150	27	7.4	11.0	14.7	9.6	
AL	450	27.5	900	1/150	50	7.4	10.2	12.8	9.6	figs. 1-4 pages 22 & 23
AL	906	115	1800	1/50	45	11.2	16.0	22.0	14.0	
GL	2537	115	600	1/120	49	14.0	20.8	32.8	18.9	
GL	2273*	27.5	900	1/25	115	43.0	46.4	86.5	44.8	figs. 1-4 pages 24 & 25

\*See inside front cover

# THREE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
BS	610	30	1800	1/750	8	.7	.84	.60	.76	figs. 1, 2, 3 page 21
FBS	2097	115	1800	1/100	35	5.6	7.3	10.4	6.8	fig. 4 page 21
AS	2554	115	900	1/100	40	11.2	13.0	24.0	12.5	
AS	1920	208	1800	1/40	60	14.0	18.4	32.0	17.6	
AL	1666	100	900	1/75	45	14.0	17.6	22.4	15.2	
AL	1882	115	1200	1/75	49	11.0	12.3	18.8	11.6	
AL	2234	240	1800	1/50	65	11.2	16.5	26.2	15.7	figs. 1-4 pages 22 & 23
AS	2219	208	3600	1/40	50	7.0	10.7	22.4	10.6	
ALL	1912	115	1800	1/25	82	22.5	25.5	38.5	24.0	
ALL	2040	208	1800	1/25	75	22.5	27.2	41.0	26.4	
ALLX	1429	208	3600	1/15	108	18.4	26.0	48.0	25.3	
G	2286	120	1800	1/15	132	38.2	42.4	80.0	41.5	
GL	1823*	208	600	1/40	107	42.0	44.0	44.0	43.0	
GL	1848*	208	900	1/25	125	45.0	53.1	68.8	52.8	
GL	2417*	208	1200	1/12	134	65.0	74.5	158.5	72.8	
GL	2167	208	1800	1/15	107	40.0	47.2	93.0	45.6	
GL	1960*	220	1800	1/5	270	112.0	120.0	127.0	117.0	
GL	2125	220	3600	1/10	122	28.0	32.0	78.0	30.0	
GL	2360*	115	3600	1/4	297	70.0	83.0	182.0	80.8	

\*See inside front cover

The magnetizing current on a three phase motor is normally high, so that the Volt-Amperes required are normally about 3 times the actual watts taken by the motor. In cases such as an electronic ampli-

fier where the Volt-Amperes from the power supply are limited, the current taken by the motor can be reduced to approximately 1/3 its value by using capacitors across the lines for power factor correction.

# DUAL VOLTAGE CONNECTION

# THREE PHASE, 60 HERTZ

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
ALLX	1569	208	3600	1/15	105	18.6	24.0	44.8	23.4	
		230	3600	1/15	105	18.6	26.0	46.4	25.0	figs. 1-4 pages 22 & 23
ALLX	1326*	208	3600	1/10	136	28.0	32.0	54.4	31.2	
		230	3600	1/10	136	28.0	34.4	54.4	32.8	
GL	1787*	208	1800	1/10	134	56.0	78.5	123.0	76.8	
		230	1800	1/10	123	56.0	81.6	126.0	78.4	figs. 1-4 pages 24 & 25
GL	1798*	208	3600	1/6	222	47.0	56.8	100.0	54.5	
		230	3600	1/6	217	47.0	54.4	94.5	52.8	

\*See inside front cover

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# SINGLE SPEED MOTORS

## SINGLE PHASE, 50 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	961	115	1500	1/350	15	1.9	2.1	1.1	2.0	1	220	figs. 1, 2, 3 page 21
FBS	897	115	1000	1/300	30	3.4	4.0	4.1	3.6	3	220	fig. 4 page 21
FBS	2473	115	1500	1/150	30	4.5	5.9	4.8	5.6	3	220	
FBS	1318	220	3000	1/75	38	4.0	4.8	6.0	4.4	1	440	
AS	2079	115	500	1/400	30	5.0	5.6	6.4	5.1	2	220	
AS	2344	115	1500	1/125	25	5.4	8.3	7.0	6.7	2.5	220	
AL	2552*	115	500	1/250	45	8.0	9.9	9.1	8.8	5	220	figs. 1-4 pages 22 & 23
AL	1676	115	1500	1/50	55	14.0	17.6	17.6	16.8	4	220	
AL	618	115	3000	1/35	50	9.5	11.7	13.5	11.4	6	220	
AL	2158	220	3000	1/35	60	9.5	12.8	12.3	10.4	5	220	
ALL	2085	230	1500	1/40	58	16.8	24.8	30.7	20.8	5	220	
G	2532	115	750	1/60	75	22.4	29.5	36.0	28.0	3	330	
G	1090	115	1500	1/15	128	45.0	48.6	61.0	46.2	8	330	figs. 1-4 pages 24 & 25
G	2333	115	3000	1/15	105	22.5	27.2	34.4	26.2	5	330	
GL	2324	115	1500	1/8	235	84.0	94.4	118.0	90.4	10	330	
GL	2181	115	3000	1/7	246	48.0	55.2	76.0	52.8	10	330	
GL	2189*	115	3000	1/5	312	68.0	72.0	81.6	69.6	10	440	

\*See inside front cover.

## THREE PHASE, 50 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
AS	2177	208	1500	1/40	60	16.0	18.9	30.6	18.2	figs. 1-4 pages 22 & 23
ALL	2103	220	1500	1/25	77	27.2	34.3	40.0	33.2	
ALLX	1545*	220	3000	1/15	111	22.4	28.0	50.5	25.6	
GL	2524*	380	3000	1/15	120	22.4	32.0	47.3	29.1	figs. 1-4 pages 24 & 25
GL	2524*	208	1000	1/18	133	55.0	63.2	126.8	60.8	
GL	1786*	220	3000	1/6	202	56.0	74.5	99.0	73.0	

\*See inside front cover.

## SINGLE PHASE, 50/60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
AS	2079	500	1/400	30	5.0	5.6	6.4	5.1	2	220	figs. 1-4 pages 22 & 23
		600	1/350	34	4.8	5.7	8.1	5.4			
G	2492	500	1/100	89	21.0	24.8	24.0	23.2	6	330	figs. 1-4 pages 24 & 25
		600	1/80	111	21.0	24.8	29.7	22.2			
GL	1959	1500	1/10	195	67.0	72.0	102.0	68.0	10	330	
		1800	1/10	149	56.0	78.5	76.8	60.0	7	330	
GL	1979*	3000	1/5	300	67.0	81.6	76.8	76.8	15	440	
		3600	1/5	285	56.0	72.0	64.8	67.2	12		

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

\*See inside front cover.

NOTE: 50/60 HERTZ MOTORS ARE NOT AS EFFICIENT AS MOTORS  
DESIGNED SPECIFICALLY FOR 50 HERTZ OR 60 HERTZ

# SINGLE SPEED MOTORS

## SINGLE PHASE, 400 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Full Load Amps	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	925	115	8000	1/200	25	.44	.6	1.15	1.0	.7	.15	330	fig. 1, 2, 3 page 21
BS	898	115	12000	1/100	25	.45	.8	1.2	1.2	.9	.22	330	
FBS	801	115	12000	1/70	40	.6	1.2	1.6	1.6	1.3	.5	330	
FBS	2357	115	24000	1/40	50	.5	1.0	2.2	1.6	1.2	.5	330	
AS	900	115	4000	1/120	90	1.0	2.1	2.8	6.8	2.6	.75	330	
AS	1308	115	6000	1/50	80	1.4	3.3	4.6	6.9	3.9	1.0	330	
AS	1222	115	8000	1/30	93	1.1	4.2	5.2	8.3	4.6	1.0	330	
AL	790	115	4000	1/75	84	1.6	3.4	5.4	4.9	5.0	.75	330	
AL	1001	208	4000	1/100	73	.8	2.5	4.1	7.7	3.2	.5	440	
AL	1147	115	8000	1/10	180	3.1	12.6	13.6	18.4	13.1	1.0	440	
AL	841	115	12000	1/15	150	2.2	5.6	7.2	7.6	6.5	1.0	330	figs. 1-4 pages 22 & 23
ALL	1194	115	4000	1/40	101	3.0	6.3	8.3	9.5	6.8	1.0	440	
ALL	1156	115	8000	1/8	228	4.7	15.7	24.0	12.0	23.2	1.0	440	
G	649	115	8000	1/10	210	3.5	12.8	24.8	27.2	13.1	1.5	440	
G	1653	115	12000	1/10	270	4.5	8.4	13.4	19.2	12.8	1.5	440	
GL	2497	115	4000	1/25	330	11.0	10.0	16.0	32.0	15.0	3.0	440	
GL	1678	115	6000	1/10	400	7.5	16.0	19.2	48.0	17.6	5.0	330	
GL	1122*	115	8000	1/6	382	8.0	21.0	35.2	41.5	28.8	3.0	440	
GL	1085	115	12000	1/5	425	7.7	16.8	23.2	25.0	20.8	6.0	220	

\*See inside front cover

## THREE PHASE, 400 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Full Load Amps	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
AS	1365	208	6000	1/35	44	.7	4.8	5.9	13.4	5.6	figs. 1-4 pages 22 & 23
AS	1207	115	6000	1/50	51	1.4	3.3	4.6	12.0	4.3	
AS	1705	115	12000	1/50	50	.80	1.7	3.0	7.6	2.4	
AL	2491	115	24000	1/4	360	5.7	10.0	12.0	53.0	11.7	
AL	1602	115	6000	1/50	68	2.1	5.6	7.5	16.0	7.0	
AL	2571	115	8000	1/25	210	3.5	5.0	6.7	42.2	6.2	
AL	1544	230	12000	1/15	110	1.0	5.6	7.3	22.0	7.0	
ALL	2298	440	12000	1/10	136	.5	8.4	9.3	21.5	9.0	
G	2284	89	6000	1/10	277	9.4	16.8	21.6	101.0	20.8	
G	1148	208	12000	1/4	365	3.85	21.0	27.2	80.0	25.0	
GL	1517	208	6000	1/25	135	1.8	6.7	8.5	42.0	8.4	figs. 1-4 pages 24 & 25
GL	2299*	440	12000	1/5	326	1.3	16.8	19.2	62.5	17.9	

\*See inside front cover

## SINGLE PHASE, ODD FREQUENCY, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	Hertz	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	915	180	4050	135	1/1000	8	.25	.35	.5	.3	.2	330	figs. 1, 2, 3 page 21
AL	1149	115	1500	100	1/75	45	9.0	11.0	12.0	10.5	1.0	440	
AL	1180	115	7200	120	1/50	50	2.8	6.5	4.8	4.8	4.0	220	
G	434	115	7200	240	1/30	95	4.2	8.0	4.5	7.2	1.0	220	

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# DUAL SPEED MOTORS

SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	388	1800	1/1200	14	.50	.75	.56	.56	1.5	220	fig. 1, 2, 3 page 21
		3600	1/600	14	.50	.65	.30	.55			
AS	2171	600	1/400	42	4.0	4.8	4.2	4.2	5	220	
		1800	1/125	42	4.5	5.7	6.7	5.6			
AS	2196	900	1/350	38	3.2	4.0	5.0	3.5	3	220	
		3600	1/90	42	3.0	5.1	3.9	4.1			
AL	1269	600	1/300	52	5.6	6.4	4.8	6.0	5	220	
		900	1/200	48	5.6	5.8	5.1	5.7			
AL	1363	600	1/400	48	4.2	6.2	4.6	5.6	4	220	
		1200	1/200	50	4.2	8.0	5.3	6.5			
AL	2490	600	1/300	50	5.6	6.7	10.4	5.9	5	220	
		1800	1/100	50	5.6	7.8	7.1	7.2			
AL	2080	600	1/375	59	4.5	5.6	5.3	5.2	6	220	
		3600	1/90	70	3.1	6.5	4.6	5.6			
AL	2482	900	1/200	41	5.6	7.0	8.0	6.5	4	220	
		1800	1/100	50	5.6	8.8	6.9	8.5			
AL	2560	900	1/200	42	5.6	6.9	6.5	7.0	3	220	
		3600	1/50	43	5.6	7.0	6.5	7.0			
AL	1932	1200	1/75	60	11.0	13.2	12.1	11.8	5	220	
		1800	1/60	55	9.5	11.8	12.9	10.5			
AL	2468	1200	1/100	63	8.4	10.8	9.7	9.8	5	220	
		3600	1/40	63	7.0	11.2	9.4	9.7			
AL	1038	1800	1/60	50	9.5	12.5	14.0	10.0	5	220	
		3600	1/40	65	7.0	10.0	9.0	8.5			
ALL	937	900	1/100	75	11.0	13.0	12.0	11.0	6	220	
		1800	1/50	80	11.0	19.0	12.0	17.0			
ALL	1271	900	1/120	80	9.4	12.5	14.1	11.7	7	220	
		3600	1/30	100	9.4	12.5	10.7	11.2			
ALL	1624	1200	1/100	62	8.4	13.6	13.6	11.8	5	220	
		3600	1/40	58	7.0	13.1	9.6	10.4			
ALL	1040	1800	1/50	60	11.0	20.0	14.0	13.0	5	220	
		3600	1/30	80	9.0	12.0	10.0	10.0			
ALLX	1316	1800	1/40	80	14.0	19.5	28.8	16.0	7	330	
		3600	1/20	100	14.0	17.6	18.4	14.7			
G	2528	600	1/200	57	8.0	9.9	9.5	8.8	4	330	
		900	1/100	55	11.2	13.6	15.0	12.6			
G	366	600	1/225	64	7.4	8.3	7.0	7.6	6	220	
		1200	1/75	80	11.0	19.2	12.1	16.8			
G	2509	600	1/200	70	8.4	10.2	9.2	9.3	4	330	
		1800	1/40	73	14.0	20.8	18.2	18.4			
G	2523	600	1/200	74	8.4	11.2	7.9	10.2	6	220	
		3600	1/40	90	6.9	12.0	9.0	9.0			
G	2581	900	1/70	73	16	19.2	28.2	17.6	4	330	
		1800	1/35	92	16	24.0	19.2	22.4			
G	2369	900	1/40	106	25	34.4	36.8	31.4	8	220	
		1800	1/20	143	25	33.6	30.4	32.0			
G	519	1200	1/60	67	14.0	16.8	26.0	16.0	6	220	
		1800	1/40	80	14.0	19.2	15.0	16.0			
G	2538	1200	1/50	85	16.8	25.0	30.0	20.8	6	330	
		3600	1/25	120	11.2	14.0	16.0	13.0			
G	2032	1800	1/30	115	18.0	24.8	26.2	23.2	6	330	
		3600	1/15	114	18.0	23.5	23.4	22.4			
GL	2780	600	1/100	75	16.0	28.0	8.0	26.0	4	330	
		1200	1/50	75	16.0	28.0	8.0	26.0			

figs. 1-4 pages 24 & 25

# DUAL SPEED MOTORS

CONTINUED FROM PAGE 10

SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
GL	2518	600	1/80	122	22.0	27.2	30.4	25.2	6	330	figs. 1-4 pages 24 & 25
		1800	1/25	138	22.0	29.6	24.0	27.2			
GL	1918	600	1/100	141	16.8	20.8	20.2	18.4	8	330	
		3600	1/10	172	28.0	35.2	31.3	31.0			
GL	2253*	600	1/60	150	28.0	33.6	35.2	32.0	10	330	
		3600	1/10	270	28.0	31.4	37.9	31.2			
GL	991	900	1/40	134	28.0	32.8	58.2	30.4	8	330	
		1800	1/15	116	38.0	52.8	47.0	46.4			
GL	2500*	900	1/30	129	40.0	48.0	45.0	44.8	10	330	
		1800	1/12	179	45.0	54.5	45.6	51.2			
GL	1371	900	1/40	156	28.0	33.0	61.0	30.4	10	330	
		3600	1/12	173	23.4	27.2	31.1	25.6			
GL	1990*	900	1/30	145	35.0	48.0	51.2	42.4	10	330	
		3600	1/6	335	45.0	54.4	43.5	49.6			
GL	1267	1200	1/25	130	34.0	40.0	40.6	38.1	6	330	
		1800	1/15	130	37.0	48.8	43.5	43.8			
GL	1623*	1200	1/15	185	55.0	62.0	58.0	61.0	10	330	
		3600	1/5	315	55.0	62.0	58.0	61.0			
GL	989	1800	1/12	175	45.0	60.0	60.0	57.2	8	330	
		3600	1/8	270	35.0	42.5	50.0	40.8			
GL	1712*	1800	1/10	195	55.0	64.0	64.0	62.0	10	330	
		3600	1/5	315	55.0	62.0	58.0	61.0			

\*See inside front cover

## SINGLE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
ALL	2028	100	900	1/200	38	6.0	8.0	7.2	7.2	5	220	figs. 1-4 pages 22 & 23
			1800	1/100	38	6.0	10.5	5.3	8.1			
ALL	2157	230	900	1/100	70	11.0	13.6	12.5	12.8	4	330	
			1800	1/40	90	14.0	20.0	17.6	18.4			
ALLX	1379	230	1800	1/40	83	14.0	26.4	27.6	19.2	2	440	
			3600	1/20	112	14.0	21.6	19.2	19.2			

## THREE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
ALLX	1401	208	1800	1/40	75	14.0	25.6	35.2	24.0	figs. 1-4 pages 22 & 23
			3600	1/20	120	14.0	22.4	30.4	19.2	
G	1865	208	1200	1/45	86	18.0	22.4	52.8	20.8	
			3600	1/15	135	18.0	22.4	43.2	20.8	
GL	2513	230	900	1/20	152	56.0	72.0	110.8	70.5	
			1800	1/10	205	56.0	77.0	120.0	75.0	
GL	1843*	208	900	1/25	148	45.0	49.5	60.0	48.0	figs. 1-4 pages 24 & 25
			3600	1/6	270	45.0	52.0	85.0	50.4	
GL	1763*	208	1200	1/20	106	40.0	53.6	83.2	51.2	
			1800	1/15	150	40.0	51.2	70.0	49.6	
GL	2206*	208	1200	1/20	133	42.0	54.4	102.0	52.7	
			3600	1/6	290	45.0	52.8	97.7	49.6	
GL	1905	208	1800	1/25	92	22.4	30.4	48.0	28.0	
			3600	1/10	160	28.0	32.0	56.0	30.4	

\*See inside front cover

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# DUAL SPEED MOTORS

SINGLE PHASE, 50 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
AL	2080	115	500	1/400	52	5.0	6.2	4.0	6.0	6	220	figs. 1-4 pages 22 & 23
			3000	1/75	70	4.5	6.2	4.6	5.6			
AL	2033	115	750	1/160	48	8.0	9.2	12.3	8.6	5	220	
			1500	1/80	50	8.0	10.4	11.6	9.9			
AL	1474	115	750	1/300	40	4.5	6.0	4.1	5.2	5	220	
			3000	1/50	60	6.5	8.5	6.0	7.5			
AL	2385	230	750	1/300	45	4.5	5.6	5.1	4.9	3	220	
			3000	1/60	75	5.6	8.1	5.4	7.3			
AL	2034	115	1000	1/150	42	6.7	11.2	8.3	9.9	5	220	
			1500	1/100	50	6.7	8.3	7.7	8.2			
AL	1736	115	1000	1/150	47	6.7	8.5	8.5	8.1	5	220	
			3000	1/50	50	6.7	8.1	6.4	7.7			
AL	1952	115	1500	1/100	55	6.7	10.9	10.5	8.8	5	220	
			3000	1/50	70	6.7	8.6	7.5	7.5			
ALL	1089	115	750	1/150	65	9.0	12.0	11.0	11.2	6	220	
			1500	1/75	65	9.0	14.5	11.0	13.5			
G	2030	115	750	1/125	82	11.0	20.0	14.7	18.4	5	330	
			1500	1/50	94	14.0	24.8	14.7	20.8			
G	2037	115	1000	1/60	70	16.8	27.2	28.5	21.6	6	330	
			3000	1/30	120	11.2	16.8	18.4	15.7			
GL	1916	115	500	1/75	138	26.0	28.8	28.2	28.0	10	330	
			1500	1/20	150	33.0	41.0	56.8	38.5			
GL	2270*	115	500	1/90	113	22.0	32.0	22.8	29.6	10	330	
			3000	1/15	210	22.0	25.0	26.4	24.0			
GL	2332*	230	750	1/20	170	67.0	75.0	72.0	72.0	10	330	
			1500	1/10	200	67.0	89.6	67.0	83.2			
GL	2013	115	1000	1/25	121	40.3	48.0	52.0	42.4	8	330	
			1500	1/25	105	26.8	40.0	27.4	34.4			
GL	2315	240	1000	1/20	130	50.0	56.0	60.8	52.7	8	330	
			3000	1/20	145	17.0	23.2	26.6	21.8			
GL	1886*	115	1000	1/20	185	50.0	65.6	50.9	60.0	10	440	
			3000	1/7	330	48.0	52.6	51.0	55.2			
GL	1442	115	1500	1/15	190	45.0	52.7	67.3	47.2	10	330	
			3000	1/8	240	42.0	46.4	61.2	45.0			
GL	1884*	115	1500	1/12	210	55.0	62.0	58.3	57.0	10	440	
			3000	1/8	260	42.0	51.2	52.5	48.0			

\*See front inside cover.

# THREE PHASE, 50 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
GL	2514	230	750	1/20	160	67.0	83.2	136.0	81.6	figs. 1-4 pages 24 & 25
			1500	1/10	200	67.0	80.0	112.0	78.4	
GL	1834*	208	1000	1/25	128	40.0	49.6	80.0	46.4	
			3000	1/8	217	42.0	60.0	80.0	54.5	

\*See front inside cover.

# THREE PHASE, 400 HERTZ, 208 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Full Load Amps	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
AS	2170	6000	1/35	75	1.1	4.8	5.9	16.0	5.7	figs. 1-4 pages 22 & 23
AS	2170	12000	1/25	90	.75	3.3	3.7	13.0	3.4	figs. 1-4 pages 22 & 23

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL

# DUAL SPEED MOTORS

SINGLE PHASE, 50/60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Hertz	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
AL	1084	50	500	1/400	41	5.0	6.7	4.2	5.9	5	220	figs. 1-4 pages 22 & 23
			1500	1/125	51	5.4	6.8	4.2	5.9			
		60	600	1/350	46	4.8	6.3	5.6	5.6			
			1800	1/100	53	5.6	6.7	5.7	6.3			
AL	1766	50	1500	1/80	43	8.4	12.9	9.0	10.9	5	330	figs. 1-4 pages 22 & 23
			3000	1/40	69	8.4	10.7	7.5	9.4			
		60	1800	1/80	46	7.0	9.6	14.4	8.0			
			3600	1/40	67	7.0	9.2	9.6	8.6			
G	2030	50	750	1/100	82	13.4	20.0	14.7	18.4	5	330	figs. 1-4 pages 22 & 23
			1500	1/50	94	13.4	24.8	14.7	20.8			
		60	900	1/100	92	11.0	15.2	24.6	13.1			
			1800	1/50	99	11.0	21.6	19.7	18.4			
G	1854	50	1000	1/70	94	15.0	18.5	13.2	16.0	6	220	figs. 1-4 pages 22 & 23
			3000	1/20	90	15.0	20.0	20.8	18.3			
		60	1200	1/60	95	15.0	20.8	17.6	18.4			
			3600	1/20	95	15.0	17.6	24.0	16.0			
G	2032	50	1500	1/40	122	18.0	28.0	27.5	24.8	6	330	figs. 1-4 pages 24 & 25
			3000	1/20	133	18.0	21.6	20.2	20.8			
		60	1800	1/30	120	18.0	23.6	33.3	22.4			
			3600	1/15	119	18.0	23.2	26.6	20.8			
GL	1505	50	750	1/60	80	22.4	28.8	34.4	26.4	8	330	figs. 1-4 pages 24 & 25
			1500	1/20	120	33.6	41.6	26.2	38.4			
		60	900	1/60	95	18.6	29.6	57.0	28.0			
			1800	1/20	115	28.0	43.2	34.6	39.2			

NOTE: 50/60 HERTZ MOTORS ARE NOT AS EFFICIENT AS MOTORS DESIGNED SPECIFICALLY FOR 50 HERTZ OR 60 HERTZ.

## TWO PHASE, ODD FREQUENCY, 115 VOLTS

Frame	Motor Type No.	Hertz	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Frame Figure No. Page No.
AL	1101	467	4670	1/60	60	3.6	4.9	10.0	4.8	figs. 1-4 pages 22 & 23
			14010	1/20	120	3.6	5.0	12.0	4.7	

## SINGLE PHASE, 400 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Full Load Amps	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
AS	2503	6000	1/80	48	.55	2.1	4.0	2.8	2.8	.40	550	figs. 1-4 pages 22 & 23
			8000	1/60	57	.80	2.1	3.5	3.2	.25		
AL	671	4000	1/75	110	2.0	3.4	4.6	5.5	4.3	.75	330	figs. 1-4 pages 22 & 23
			12000	1/25	110	1.6	3.4	4.3	4.0	.75		
AL	1257	6000	1/60	100	2.0	2.8	3.7	8.5	3.2	.75	440	figs. 1-4 pages 22 & 23
			12000	1/20	138	2.4	4.2	6.1	6.7	5.1	.75	
AL	1803	8000	1/35	81	1.3	3.4	4.6	4.4	4.0	.75	330	figs. 1-4 pages 22 & 23
			12000	1/25	112	1.7	3.4	4.3	4.0	.75		

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# MULTIPLE SPEED MOTORS

SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
G	938	600	1/250	78	6.7	8.6	6.9	7.7	6		
		1200	1/100	86	8.4	11.5	12.5	10.5	6	220	
		3600	1/50	122	5.6	10.7	6.9	9.3	6		
G	371	900	1/200	60	5.6	6.7	9.1	6.1	5		
		1800	1/60	75	9.3	14.9	10.4	13.7	5	220	
		3600	1/30	115	9.3	13.3	9.3	11.4	8		
G	957	900	1/150	70	7.5	9.6	14.2	8.6	6		
		1800	1/50	90	11.2	16.3	13.6	15.2	6	220	
		3600	1/40	110	7.2	12.6	8.0	12.0	6		
G	1243	1200	1/75	80	11.2	14.2	12.8	12.2	10		
		1800	1/60	95	9.5	21.6	13.8	16.0	10	220	
		3600	1/40	120	7.1	13.6	14.2	11.7	10		
GL	992	600	1/200	75	8.4	12.2	7.4	10.6	8		
		1800	1/50	85	11.2	20.0	16.0	17.4	8	220	
		3600	1/25	150	11.2	20.8	17.2	19.2	8		
GG	492	900	1/90	125	12.0	15.0	15.5	13.3	10		
		1800	1/30	175	18.6	35.0	18.2	25.5	10	220	
		3600	1/20	250	14.0	30.4	13.5	22.3	16		
GG	1152	900	1/50	76	22.5	26.0	35.0	24.5	3		
		1800	1/30	92	18.5	26.4	26.2	19.2	6	330	
		3600	1/20	117	14.0	19.5	23.2	18.5	6		
GGLX	1939	900	1/50	76	22.5	26.0	35.0	24.5	3		
		1800	1/15	146	37.0	49.6	45.5	40.0	8	330	
		3600	1/10	230	28.0	35.2	41.6	32.8	8		
GG	2071	600	1/125	91	13.0	16.0	23.8	15.0	6		
		900	1/75	92	15.0	19.2	22.7	17.6	6		
		1200	1/50	93	17.0	24.8	19.2	22.9	6	330	
GG	1013	1800	1/40	94	14.0	18.4	20.0	16.8	6		
		600	1/200	88	8.4	11.2	12.8	10.4	6		
		1200	1/50	91	16.8	23.2	20.2	21.1	6	330	
GG	449	1800	1/25	88	22.4	32.8	31.6	24.0	6		
		3600	1/25	112	11.2	15.2	19.5	13.9	6		
		600	1/225	64	7.4	8.3	7.0	7.6	6		
GG	449	900	1/200	60	5.6	6.7	9.1	6.1	5		
		1200	1/75	80	11.2	19.2	12.1	16.8	6	220	
		1800	1/60	75	9.5	14.9	10.4	13.7	5		
GG	1153	3600	1/30	115	9.3	13.3	9.3	11.4	8		
		600	1/200	57	8.0	9.9	15.7	8.8	4		
		900	1/100	55	11.2	13.6	15.0	12.6	4		
GG	1153	1200	1/75	80	11.2	14.2	12.8	12.2	10	330	
		1800	1/60	95	9.5	21.6	13.8	16.0	10		
		3600	1/40	120	7.1	13.6	14.2	11.7	10		

SINGLE PHASE, 50 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
GG	2304	750	1/60	95	22.0	25.5	43.0	24.0	8		
		1500	1/30	117	22.0	27.0	34.0	26.0	8	330	
		3000	1/25	105	13.0	18.0	25.0	16.0	8		figs. 1 & 2 page 24

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# MULTIPLE SPEED MOTORS

SINGLE PHASE, 50/60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed Hertz	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
G 2367	60	900	1/60	136	18.0	28.0	49.5	25.6	10		
		1800	1/30	140	18.0	22.7	24.3	21.5	10	330	
	50	3600	1/15	150	18.0	22.4	26.2	21.0	10		figs. 1-4 pages 24 & 25
		750	1/72	118	18.0	23.3	33.6	21.1	10		
		1500	1/36	140	18.0	27.5	22.7	24.8	10	330	
		3000	1/18	150	18.0	25.6	21.9	24.3	10		
GGL 1943*	60	600	1/100	111	17.0	24.8	29.6	22.2	6		
		1800	1/20	178	28.0	58.5	45.4	43.2	12	330	
	50	3600	1/10	230	28.0	43.2	34.2	36.0	12		figs. 1 & 2 page 24
		500	1/100	90	21.0	24.8	24.0	23.2	6		
		1500	1/20	195	36.0	63.2	51.8	55.2	15	330	
		3000	1/10	245	36.0	41.6	39.0	38.5	15		

\*See inside front cover

NOTE: 50/60 HERTZ MOTORS ARE NOT AS EFFICIENT AS MOTORS DESIGNED SPECIFICALLY FOR 50 HERTZ OR 60 HERTZ.

# VARIABLE SPEED MOTORS

TWO OR THREE PHASE, VARIABLE FREQUENCY, VARIABLE VOLTS

Frame	Motor Type No.	Phase	Volts/Hertz	Voltage Range	Poles	RPM Speed Range	Frequency Range	Rated Torque Oz. In.	Frame Figure No. Page No.
G	1324	2	.70	6.3-250	12	90-3600	9-360	10.0	figs. 1-4 pages 24 & 25
AL	425	2	.92	8.2-330	8	135-5400	9-360	4.0	
AL	450	2	.46	4.1-165	8	135-5400	9-360	4.0	figs. 1-4 pages 22 & 23
GL	1863	2	1.92	57.5-460	8	450-3600	30-240	20.0	figs. 1-4 pages 24 & 25
AL	1789	2	.29	26-121	6	1800-8400	90-420	6.0	
AL	906	2	1.92	19.2-115	4	300-1800	10-60	7.0	figs. 1-4 pages 22 & 23
AL	1666	3	1.67	16.6-308	8	150-2775	10-185	8.0	
GL	2386	3	2.00	24-240	6	220-2400	11-120	25.0	figs. 1-4 pages 24 & 25
AL	2234	3	4.00	40-260	4	300-1950	10-65	12.0	figs. 1-4 pages 22 & 23
GL	2299	3	1.10	220-440	4	6000-12000	200-400	16.0	figs. 1-4 pages 24 & 25
AL	2006	3	4.0	40-260	2	600-3900	10-65	14.0	figs. 1-4 pages 22 & 23
GL	2125	3	3.67	66-403	2	1080-6600	18-110	20.0	figs. 1-4 pages 24 & 25

# A. C. HYSTERESIS SYNCHRONOUS MOTORS USED IN CONJUNCTION WITH D.C. INVERTERS

ONE OR TWO PHASE, ODD FREQUENCY, ODD VOLTS

Frame	Type	Phase	Hertz	Volts D.C.	Speed RPM	Poles	HP	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Pull In Torque Oz. In.	Cap. Value MFD	Cap. Voltage	Frame Fig. No. Page No.	
BS	2591	1	60	12	1800	4	1/200	3.0	3.3	4.0	3.1	100.	25	figs. 1, 2, 3 page 21
AS	2247	1	60	125	1200	6	1/90	9.3	13.3	8.5	13.1	1.0	330	
AS	2389	1	60	125	1800	4	1/70	8.0	8.6	10.2	8.2	1.5	330	figs. 1-4 pages 22 & 23
AS	2443	1	150	125	3000	6	1/45	8.0	9.0	6.1	8.5	0.5	440	
AL	2413	1	60	125	900	8	1/140	8.0	8.8	11.3	8.2	1.5	330	
G	2277	1	30	125	300	12	1/425	8.0	14.4	16.8	12.8	2.5	330	figs. 1-4 pages 24 & 25
G	2442	1	60	125	600	12	1/150	9.6	18.9	13.4	17.3	2.0	330	
BS	2460	2	240	28	7200	4	1/50	2.8	3.5	4.5	3.0	—	—	figs. 1, 2, 3 page 21

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# POLARIZED SYNCHRONOUS MOTORS

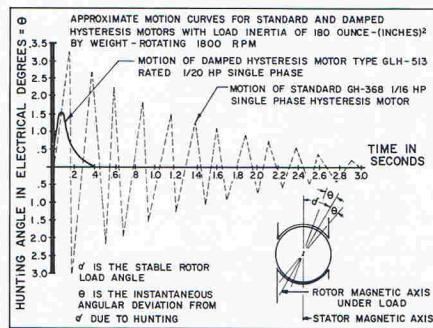
In many applications, the motor shaft must synchronize in a particular position relative to line voltage. To overcome the disadvantage of the Hysteresis motor's lack of phasing, the Polarized Hysteresis unit has been developed. It is superior

to the Reluctance motor in that the Polarized Hysteresis motor will lock in at one-half the points. In the two pole Reluctance motor there are two positions of lock-in 180° apart, but in the Polarized motor there is one point.

## SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Lock In Point	Accuracy	Frame Figure No. Page No.
BS	2038	1800	1/350	10	1.6	3.6	1.6	1.7	1	220	2@180° ±2°	figs. 1, 2, 3 page 21
BS	2200	3600	1/250	10	1.1	1.3	1.6	1.3	1	220	1 ±2°	
FBS	1538	1800	1/250	28	2.2	8.8	5.0	5.9	3	220	2@180° ±2°	fig. 4 page 21
FBS	1742	3600	1/250	27	1.1	5.9	1.6	1.8	2	220	1 ±2°	

## STABILIZED HYSTERESIS MOTORS FOR LARGE INERTIA LOADS



The early designs of the Hysteresis Synchronous motor, with low torques and soft couplings, showed little tendency to hunt. With the availability of new materials and advanced design techniques, the torque available from a given motor size increased tenfold (1/40 horsepower in 1947 to 1/4 horsepower in 1967). With the increase in torque, difficulties in hunting are proportionally greater.

In 1950, ELINCO announced a high torque Hysteresis motor with fully damped motion for large loads. Since then, the stabilized motor has become available in all frame sizes, with various speed and voltage variations, as well as multi-speed units.

This type of motor has application when an excellent degree of rotational stability is required. Its use permits higher basic motor speed for a given load inertia without increasing hunting and, therefore, greater power out for a fixed motor size. For the same frame size, the non-hunting feature reduces horsepower approximately 30%, mainly in the effect on pull in torque.

The curve at left shows the comparison between a standard 1/16 horsepower Hysteresis motor and the newer non-hunting unit. It may be seen that the non-hunting motor not only radically reduces the duration of any oscillation but cuts the magnitude of the initial swing about 50%.

The standard motor is capable of damping out after one oscillation a connected load inertia of approximately 9 oz. in.<sup>2</sup> by weight, as against a value of 180 oz. in.<sup>2</sup> for the motor with damped motion.

## SINGLE SPEED

## SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
FBS	1284	3600	1/225	24	1.2	1.5	3.2	1.4	1	330	fig. 4 page 21
AS	1858	1800	1/115	45	5.0	5.2	15.2	5.1	3	330	
AL	970	1800	1/50	52	11.0	12.0	19.0	11.5	3	220	figs. 1-4 pages 22 & 23
AL	2077	3600	1/50	53	5.6	8.1	9.2	7.5	3	330	
GL	2905	1800	1/150	70	11.0	13.0	28.0	12.0	6	220	figs. 1-4 pages 24 & 25
GL	2250*	1800	1/15	105	37.3	64.0	44.0	51.2	6	330	
GL	2251*	3600	1/10	200	28.0	46.6	48.0	33.6	8	330	
GL	2265*	3600	1/6	250	46.6	51.2	52.8	48.0	10	330	

\*See inside front cover.

## DUAL SPEED

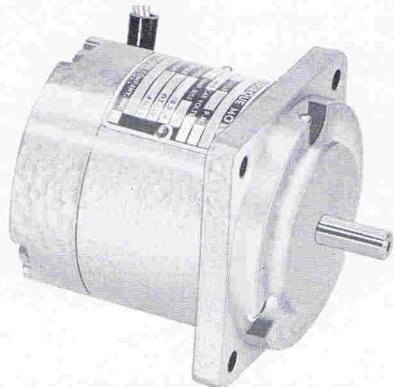
## SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
ALL	2027	900	1/225	62	5.6	6.5	16.0	5.9	4	220	figs. 1-4 pages 22 & 23
		1800	1/90	71	7.2	7.8	13.1	7.3	4		
ALL	2168	900	1/250	40	4.5	5.7	8.5	5.2	2	220	figs. 1-4 pages 24 & 25
		1800	1/100	49	5.8	6.8	8.3	6.4	2		
ALL	1974	900	1/200	57	5.6	7.2	10.2	6.7	5	220	
		1800	1/75	66	7.5	9.6	11.2	8.8	5		
ALL	1600	1800	1/60	61	9.6	11.8	16.1	9.8	5	220	
		3600	1/40	80	7.0	8.5	8.5	7.0	5		
GL	2356	600	1/150	90	11.2	15.2	25.6	14.1	5	330	figs. 1-4 pages 24 & 25
		1200	1/50	118	21.0	24.8	24.0	23.2	5		
GL	2499	1800	1/25	110	22.2	29.8	30.4	27.8	5	440	
		3600	1/15	160	18.7	29.2	27.2	27.5	5		

# FRAME PICTURES

2-1/4 BASIC DIAMETER

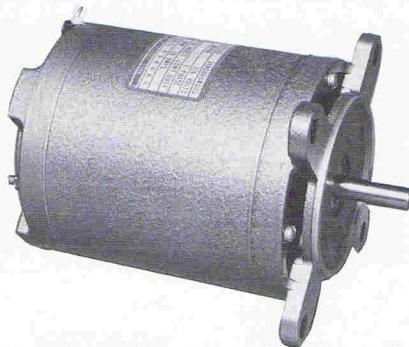
MOUNTING FLANGE "J"



BSH FIGURE 3 PAGE 21

3-3/8 BASIC DIAMETER

MOUNTING FLANGE "J"



ALHJ FIGURE 1 PAGE 22

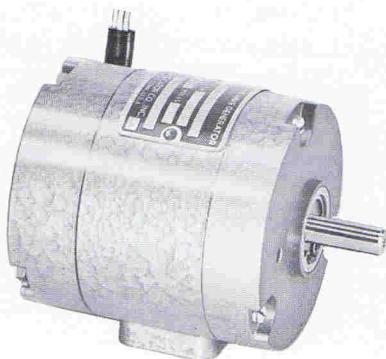
4-3/8 BASIC DIAMETER

MOUNTING FLANGE "J"



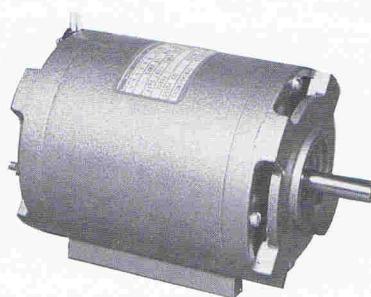
GLHJRN FIGURE 1 PAGE 24

MOUNTING FACE OR BASE



BSH FIGURE 1 PAGE 21

MOUNTING BASE "B"



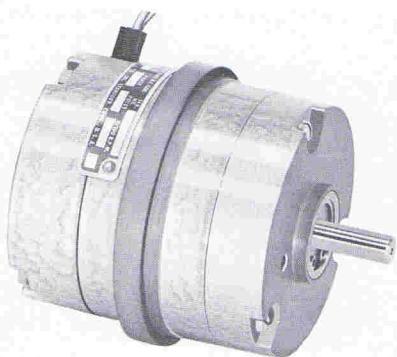
ALHB FIGURE 2 PAGE 22

MOUNTING BASE "B"



GLHNNB FIGURE 2 PAGE 24

MOUNTING FACE OR RING



FSH FIGURE 2 PAGE 21

MOUNTING PILOT "F"



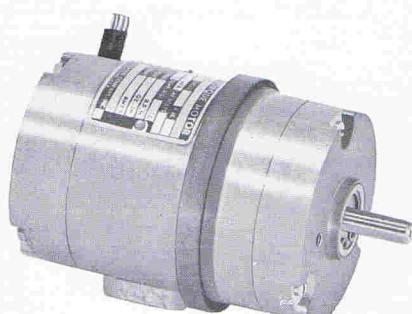
ALHF FIGURE 3 PAGE 23

MOUNTING PILOT "F"



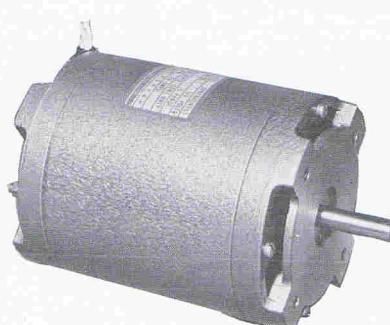
GLHFRN FIGURE 3 PAGE 25

MOUNTING FACE BASE RING



FBSH FIGURE 4 PAGE 21

MOUNTING FACE NO PILOT "M"



ALHM FIGURE 4 PAGE 23

MOUNTING FACE NO PILOT "M"



GLHMRN FIGURE 4 PAGE 25

OMIT "H" IN ABOVE FRAME TYPES FOR SALIENT POLE INDUCTION SYNCHRONOUS MOTORS (PAGE 18 & 19)

# SALIENT POLE INDUCTION SYNCHRONOUS MOTORS

The Salient Pole Induction or Reluctance motor consists of a wound stator and a rotor similar to an Induction rotor. Pole saliencies are formed on the rotor by removing rotor teeth. This type of motor starts and accelerates through sub-synchronous speeds as an Induction motor, but runs at synchronous speed as a Reluctance motor.

## CHARACTERISTICS OF THE SALIENT POLE TYPE SPEED

The angular velocity of this motor, once at synchronous speed, is constant and hunting, variations of angular velocity, is at a minimum. The relative rotor position or load angle will assume a new position with a load variation.

The number of poles and line frequency determine the rotor speed as in the Hysteresis Synchronous motor. The formula can be found on page 4. The maximum number of poles, however, is limited by the number of pole saliencies practical. The salient pole motor is available in two, four and, in the ELINCO "G" and "GL" frame, six poles. Due to pole saliencies required for each speed, this type of motor cannot be provided as a multi-speed unit.

## LOAD INERTIA

In the use of Salient Pole Induction motors, load inertia is an important factor. As the rotor approaches synchronous speed, there is a critical point at which the motor must accelerate the load and rotor inertia into synchronous operation. This transition must take place within the time the rotor rotates through one-half of a pole pitch. It is for this reason that a salient pole motor may start a load which it cannot pull into synchronism. With an inertia load, the size of the salient pole motor required may be much larger than a Hysteresis motor since the synchronous pull in torque must be selected to assure transition from sub-synchronous to synchronous speed.

## STARTING TORQUE

The starting torque, due to the pole saliencies, is subject to wide variations with rotor position.

## NOISE AND VIBRATION

The salient pole Induction motor operates at an inherently higher noise and vibration level than the Hysteresis Synchronous motor. The non-uniform magnetic path caused by the pole saliencies, accounts for this higher level. It should be remembered that this is a magnetic, rather than mechanical phenomena. ELINCO designs for minimum noise and vibration.

## PHASING

The salient pole Induction motor will phase into synchronous speed at fixed angular position. On two pole units, the rotor will phase in at two positions, 0° and 180° apart; a four pole motor will phase in at four positions 0°, 90°, 180° and 270° apart.

## SUMMARY

The inherent characteristics of the salient pole Induction motor are:

- Motor rotates at constant speed, regardless of load and voltage variations within the rating of the motor.
- Motor can phase in at definite positions with respect to shaft.
- Although the Hysteresis motor quickly damps the hunting to a minimum, there are applications where only minute hunting is permissible. On such applications, the salient pole motor should be used.
- Wide variations in starting torque, dependent on rotor position.
- Capable of synchronizing a limited load inertia.
- Inherent noise and vibration level higher than the Hysteresis Synchronous motor.
- Can be supplied as single speed motor only.

## SALIENT POLE INDUCTION SYNCHRONOUS MOTOR

### SINGLE PHASE, 60 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Pull Out Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
FBS	2022	1800	1/140	29	4.0	7.3	4.8	5.1	3	220	fig. 4 page 21
AS	2228	1800	1/50	42	11.2	16.0	16.0	13.6	4	220	figs. 1-4 pages 22 & 23
ALL	1762	1200	1/75	52	11.0	15.7	11.0	14.7	2	440	
G	1996	1800	1/25	108	22.4	46.4	19.4	36.0	10	330	figs. 1-4 pages 24 & 25

## SPLIT PHASE

### SINGLE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Frame Figure No. Page No.
GS	248	230	1800	1/30	80	18.6	40.0	21.0	32.0	
GS	197	115	1800	1/15	100	37.0	45.0	48.0	48.0	figs. 1-4 pages 24 & 25
GS	286	115	3600	1/20	140	14.4	42.0	18.5	18.5	

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

# SALIENT POLE INDUCTION SYNCHRONOUS MOTOR

## DUAL CAPACITOR

## SINGLE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
GS	572	115	1200	1/15	120	56.0	70.0	66.0	70.0	†5/10‡‡	220	
GS	295	115	1800	1/12	117	46.5	51.0	50.0	51.0	8/8	220	
GS	330	230	1800	1/25	52	22.0	45.0	28.0	41.0	†1.5/3.5‡‡	330	figs. 1-4 pages 24 & 25
GS	342	230	1800	1/12	130	46.0	93.0	51.0	55.0	†2/4‡‡	220	
GS	333	115	3600	1/15	130	19.0	22.0	26.0	27.0	†6/24‡‡	220	

†Running Capacitor. ‡‡Starting Capacitor.

## THREE PHASE, 60 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Frame Figure No. Page No.
AL	267	115	1800	1/50	50	11.1	40	12.5	12.5	
AL	201	220	1800	1/75	25	7.5	10	9.5	10.5	figs. 1-4 pages 22 & 23
G	234	220	1800	1/20	68	28.0	144	34.0	36.0	figs. 1-4 pages 24 & 25

## SINGLE PHASE, 30 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	757	1800	1/500	9.5	1.1	2.4	1.3	2.2	2	220	figs. 1, 2, 3 page 21

## SPLIT PHASE

## SINGLE PHASE, 50 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Frame Figure No. Page No.
GS	647	1500	1/20	72	34	50	48	54	figs. 1-4 pages 24 & 25

## SINGLE PHASE, 50 HERTZ, ODD VOLTS

Frame	Motor Type No.	Volts	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Cap Value Mfd.	Cap Voltage	Frame Figure No. Page No.
BS	844	115	1500	1/350	15	2.0	2.3	2.3	2.5	1.00	220	figs. 1, 2, 3 page 21
AS	328	230	1500	1/100	38	6.7	9.5	7.5	9.5	1.25	440	figs. 1-4 pages 22 & 23

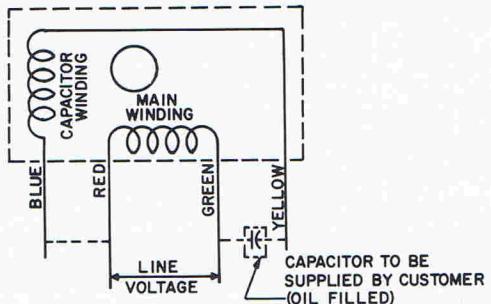
## TWO PHASE, 80 HERTZ, 115 VOLTS

Frame	Motor Type No.	Speed RPM	HP	Full Load Watts	Rated Torque Oz. In.	Starting Torque Oz. In.	Pull In Torque Oz. In.	Pull Out Torque Oz. In.	Frame Figure No. Page No.
AS	1023	4800	1/30	60	8.0	40	10	13	
AL	1022	4800	1/20	65	11.2	60	13	16	figs. 1-4 pages 22 & 23

SEE PAGE 20 FOR WIRING DIAGRAMS ON ALL UNITS

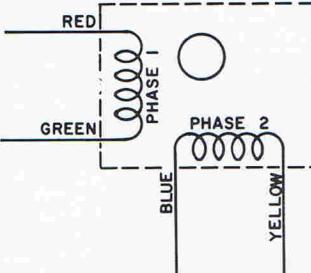
# STANDARD CONNECTION DIAGRAMS

**A** SINGLE SPEED MOTOR  
FOUR LEAD, CAPACITOR TYPE CONNECTION  
REVERSIBLE ROTATION



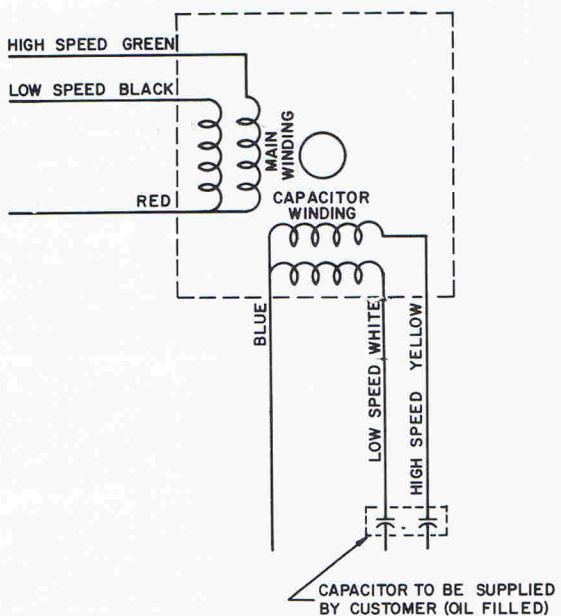
NOTE  
CONNECTION SHOWN FOR COUNTERCLOCKWISE ROTATION FACING LEAD END. TO REVERSE ROTATION INTERCHANGE RED AND GREEN LEADS.

**C** SINGLE SPEED MOTOR  
FOUR LEAD, TWO PHASE CONNECTION  
REVERSIBLE ROTATION



NOTE  
TO REVERSE ROTATION INTERCHANGE RED AND GREEN LEADS.

**B** DUAL SPEED MOTOR  
SIX LEAD, CAPACITOR TYPE CONNECTION  
REVERSIBLE ROTATION

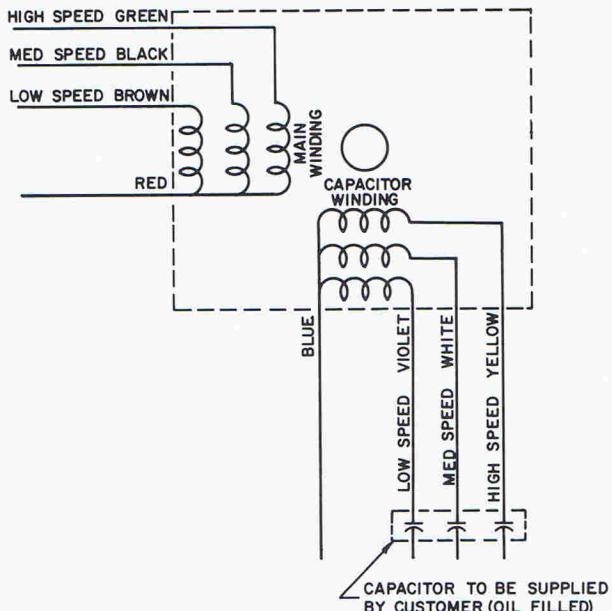


NOTE  
COUNTERCLOCKWISE ROTATION FACING LEAD END.  
CONNECT BLUE AND RED TO ONE SIDE OF LINE.

HIGH SPEED  
CONNECT YELLOW TO CAPACITOR.  
CONNECT GREEN AND CAPACITOR TO OTHER SIDE OF LINE.  
TO REVERSE ROTATION INTERCHANGE RED AND GREEN LEADS.

LOW SPEED  
CONNECT WHITE TO CAPACITOR.  
CONNECT BLACK AND CAPACITOR TO OTHER SIDE OF LINE.  
TO REVERSE ROTATION INTERCHANGE RED AND BLACK LEADS.

**D** THREE SPEED MOTOR  
EIGHT LEAD, CAPACITOR TYPE CONNECTION  
REVERSIBLE ROTATION



NOTE  
COUNTERCLOCKWISE ROTATION FACING LEAD END.  
CONNECT BLUE AND RED TO ONE SIDE OF LINE.

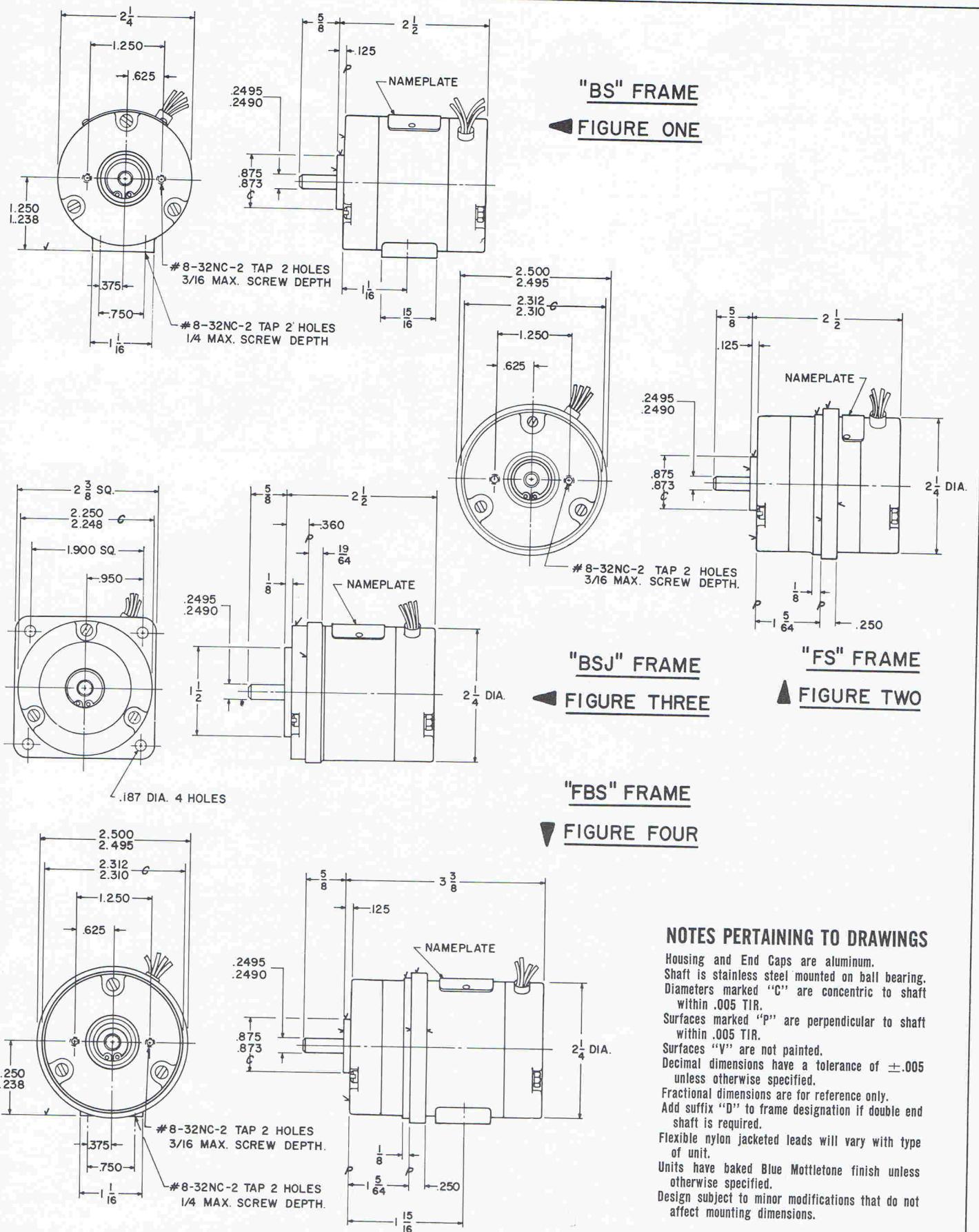
HIGH SPEED  
CONNECT YELLOW TO CAPACITOR.  
CONNECT GREEN AND CAPACITOR TO OTHER SIDE OF LINE.  
TO REVERSE ROTATION INTERCHANGE RED AND GREEN LEADS.

MED SPEED  
CONNECT WHITE TO CAPACITOR.  
CONNECT BLACK AND CAPACITOR TO OTHER SIDE OF LINE.  
TO REVERSE ROTATION INTERCHANGE RED AND BLACK LEADS.

LOW SPEED  
CONNECT VIOLET TO CAPACITOR.  
CONNECT BROWN AND CAPACITOR TO OTHER SIDE OF LINE.  
TO REVERSE ROTATION INTERCHANGE RED AND BROWN LEADS.

LEADS MAY BE IDENTIFIED BY TRACER OR SOLID COLORS

### **"BS"- "FS"- "BSJ"- "FBS" FRAMES**



## **NOTES PERTAINING TO DRAWINGS**

Housing and End Caps are aluminum.  
Shaft is stainless steel mounted on ball bearing.  
Diameters marked "C" are concentric to shaft  
within .005 TIR.  
Surfaces marked "P" are perpendicular to shaft  
within .005 TIR.  
Surfaces "V" are not painted.  
Decimal dimensions have a tolerance of  $\pm .005$   
unless otherwise specified.  
Fractional dimensions are for reference only.  
Add suffix "D" to frame designation if double end  
shaft is required.  
Flexible nylon jacketed leads will vary with type  
of unit.  
Units have baked Blue Mottletone finish unless  
otherwise specified.  
Design subject to minor modifications that do not  
affect mounting dimensions.

"AS" - "AL" - "ALL" - "ALLX" FRAMES

ASJ - ALJ - ALLJ - ALLXJ

ASJT - ALJT - ALLJT - ALLXJT

FLANGE MOUNTING

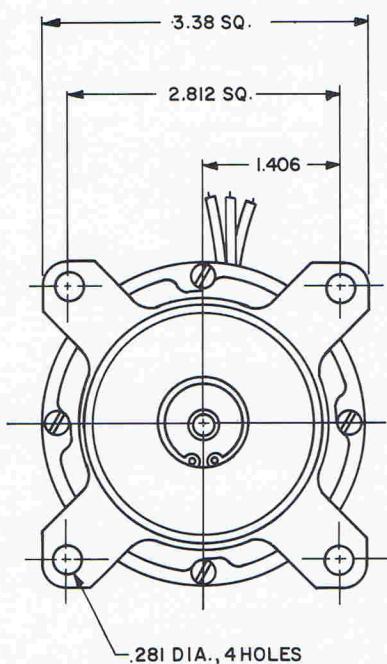
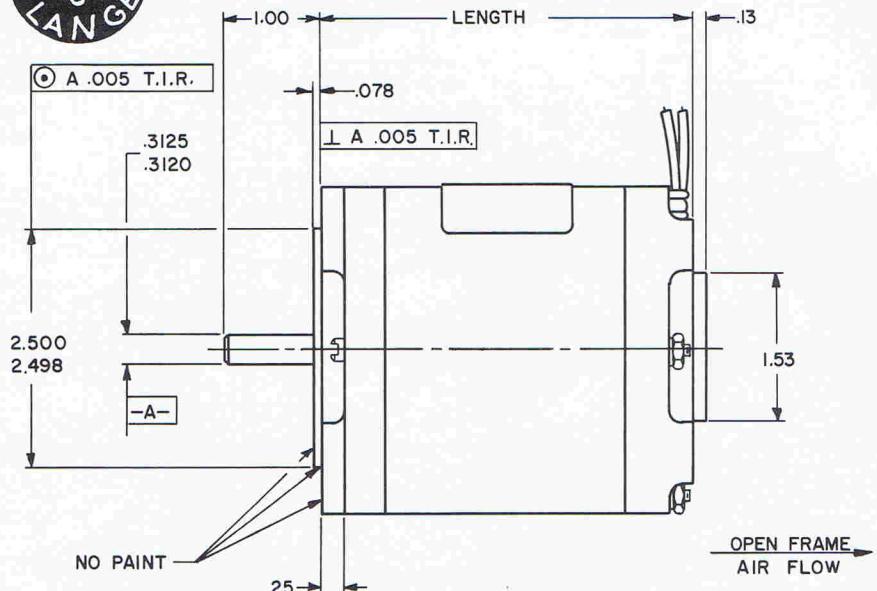


FIGURE  
J  
FLANGE



NOTE

- 1.-ALUMINUM FRAME
- 2-STAINLESS STEEL SHAFT
- 3-BALL BEARING CONSTRUCTION
- 4-MOTOR LEADS 12" LONG
- 5-FINISH-MOTTLETONE BLUE
- 6-SHAFT RUNOUT,.001 T.I.R.

ASB - ALB - ALLB - ALLXB

ASBT - ALBT - ALLBT - ALLXBT

BASE MOUNTING

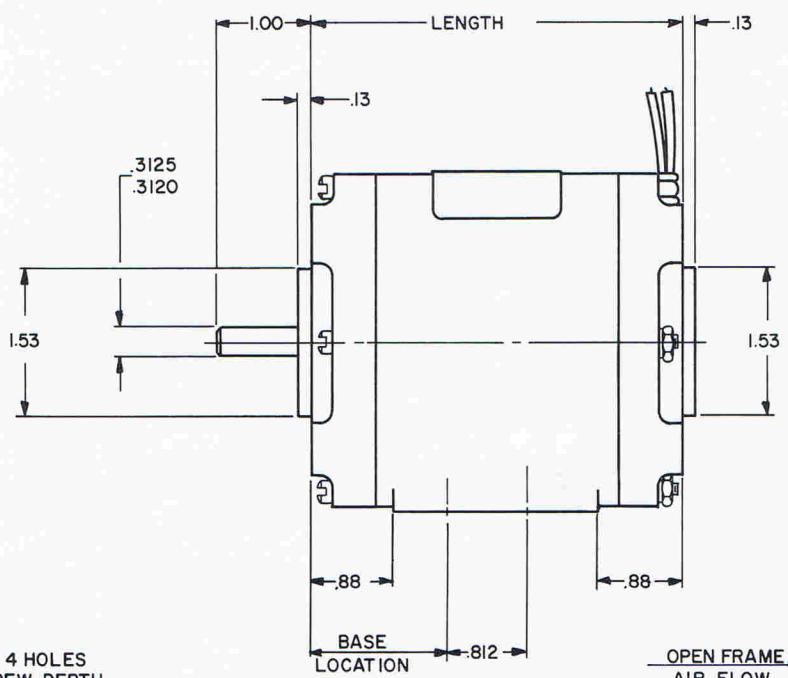
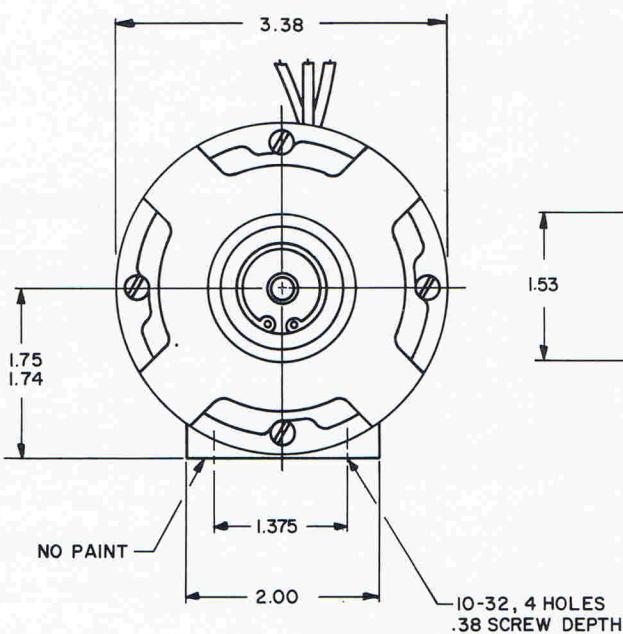
FRAME	LENGTH	BASE LOCATION
ASJ	ASB	1.50
ALJ	ALB	1.50
ALLJ	ALLB	1.75
ALLXJ	ALLXB	1.75
ASJT	ASBT	1.50
ALJT	ALBT	1.50
ALLJT	ALLBT	1.75
ALLXJT	ALLXBT	1.75

T = THERMAL PROTECTOR

TOLERANCES

.XX ± .03  
.XXX ± .005

FIGURE  
B  
BASE



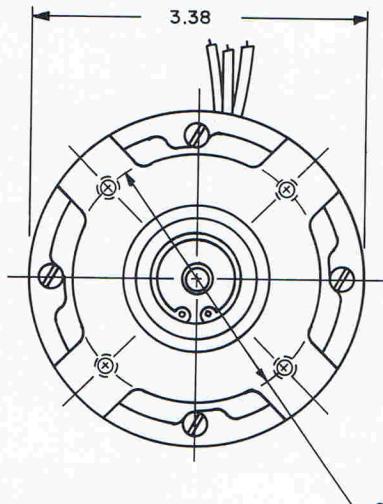
"AS"- "AL"- "ALL"- "ALLX" FRAMES

ASF - ALF - ALLF - ALLXF

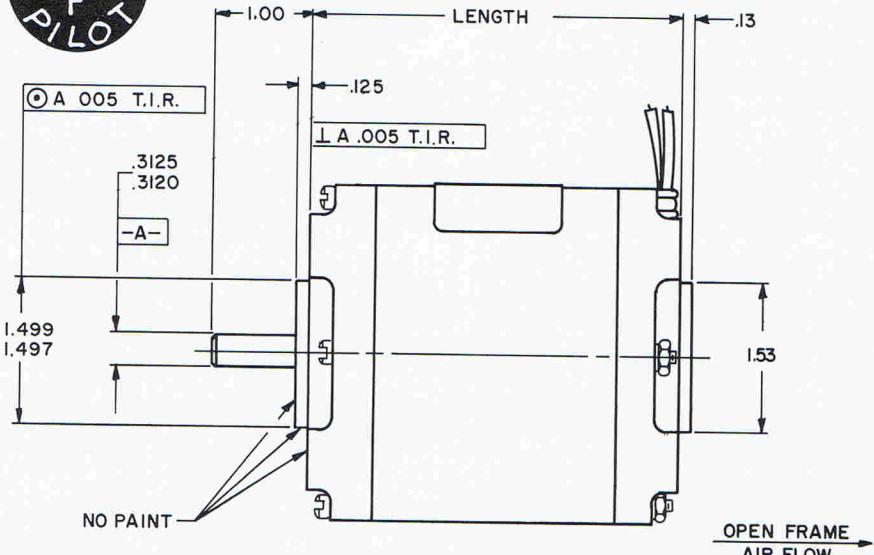
ASFT - ALFT - ALLFT - ALLXFT

FACE MOUNTING, WITH PILOT

FIGURE  
3  
F  
PILOT



2.625    4 HOLES  
10-24    90° APART  
.38 SCREW DEPTH



NOTE

- 1.-ALUMINUM FRAME
- 2.-STAINLESS STEEL SHAFT
- 3.-BALL BEARING CONSTRUCTION
- 4.-MOTOR LEADS 12" LONG
- 5.-FINISH-MOTTLETOONE BLUE
- 6.-SHAFT RUNOUT,.001 T.I.R.

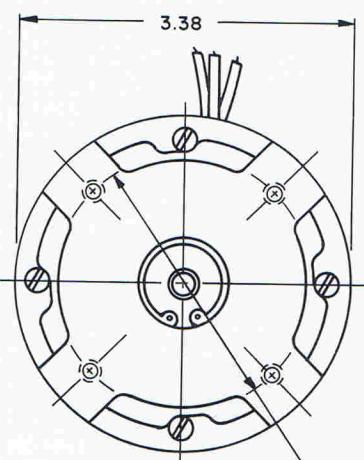
FRAME	LENGTH
ASF	ASM
ALF	ALM
ALLF	ALLM
ALLXF	ALLXM
ASFT	ASMT
ALFT	ALMT
ALLFT	ALLMT
ALLXFT	ALLXMT

T = THERMAL PROTECTOR

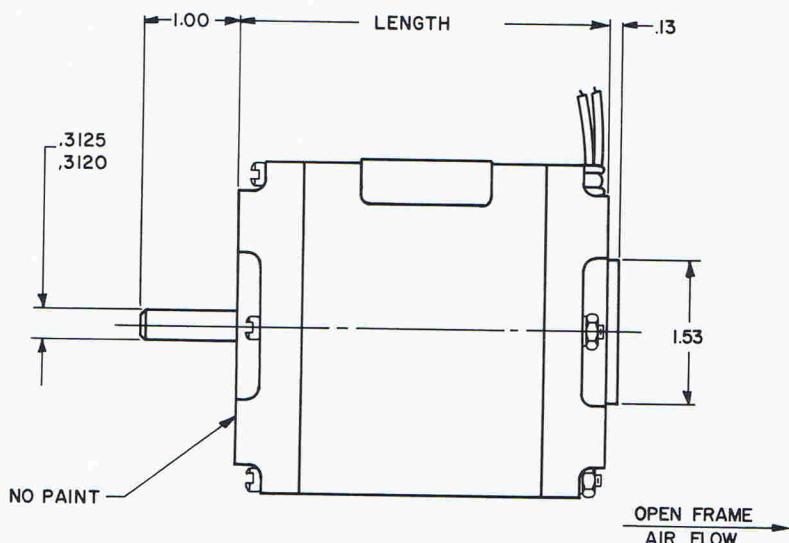
TOLERANCES

.XX     $\pm .03$   
.XXX     $\pm .005$

FIGURE  
4  
M  
FACE



2.625    4 HOLES  
10-24    90° APART  
.38 SCREW DEPTH



ASM - ALM - ALLM - ALLXM

ASMT - ALMT - ALLMT - ALLXMT

FACE MOUNTING, NO PILOT

# "G"- "GL" - "GLL" - "GG" - "GGL" FRAMES

GJRN-GLJRN-GLLJRN-GGJRN-GGLJRN

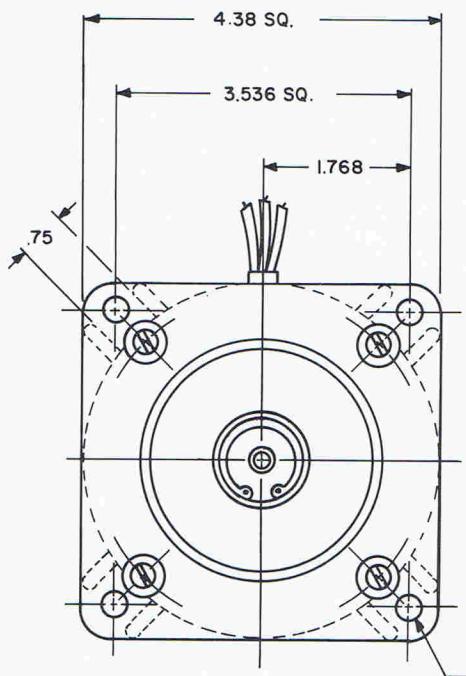
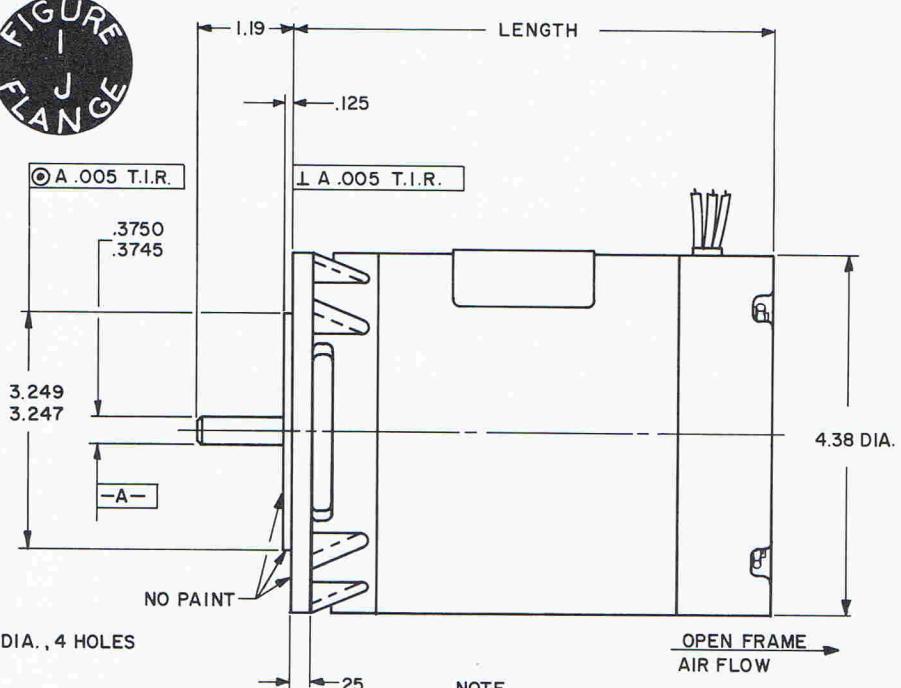


FIGURE  
I  
FLANGE



FRAME	LENGTH	BASE LOCATION
GJRN	5.81	
GLJRN	6.81	
GLLJRN	8.38	
GGJRN	8.44	
GGLJRN	9.81	
GNNB	5.88	1.25
GLNNB	6.88	1.25
GLLNNB	8.44	2.50
GGNNB	8.50	2.68
GGLNNB	9.88	3.38

## TOLERANCES

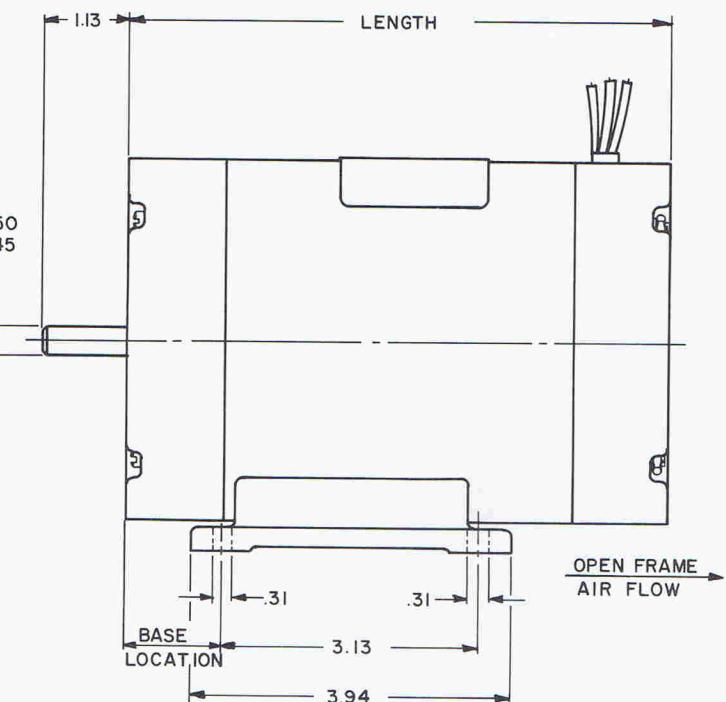
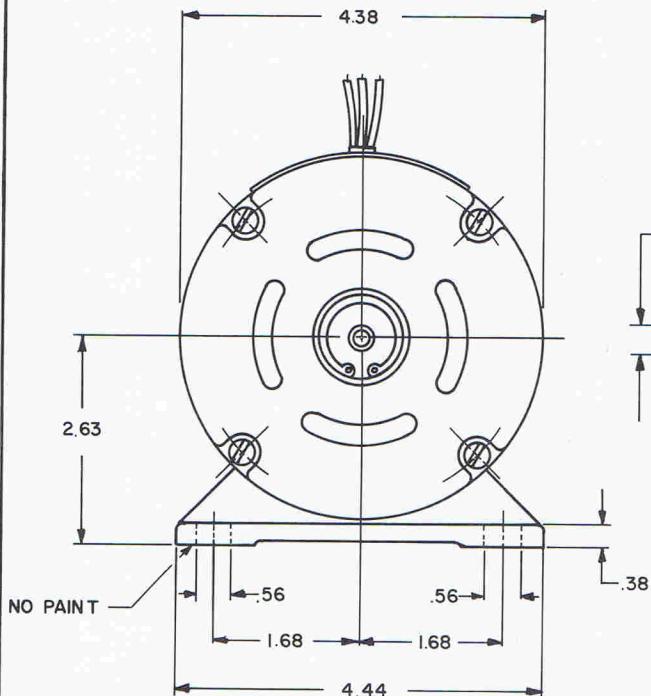
.XX ± .03  
.XXX ± .005

FIGURE  
2  
BASE

## NOTE

- 1.- ALUMINUM FRAME
- 2.- STAINLESS STEEL SHAFT
- 3.- BALL BEARING CONSTRUCTION
- 4.- MOTOR LEADS 12" LONG
- 5.- FINISH - MOTTLETONE BLUE
- 6.- SHAFT RUNOUT, .001 T.I.R.

GNNB-GLNNB-GLLNNB-GGNNB-GGLNNB  
BASE MOUNTING



"G"--"GL"--"GLL" FRAMES

GFRN-GLFRN-GLLFRN

FACE MOUNTING, WITH PILOT

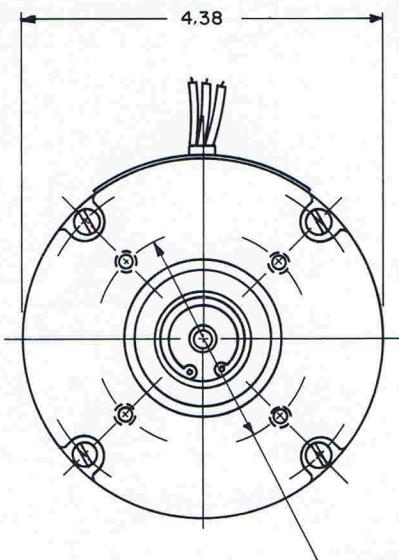
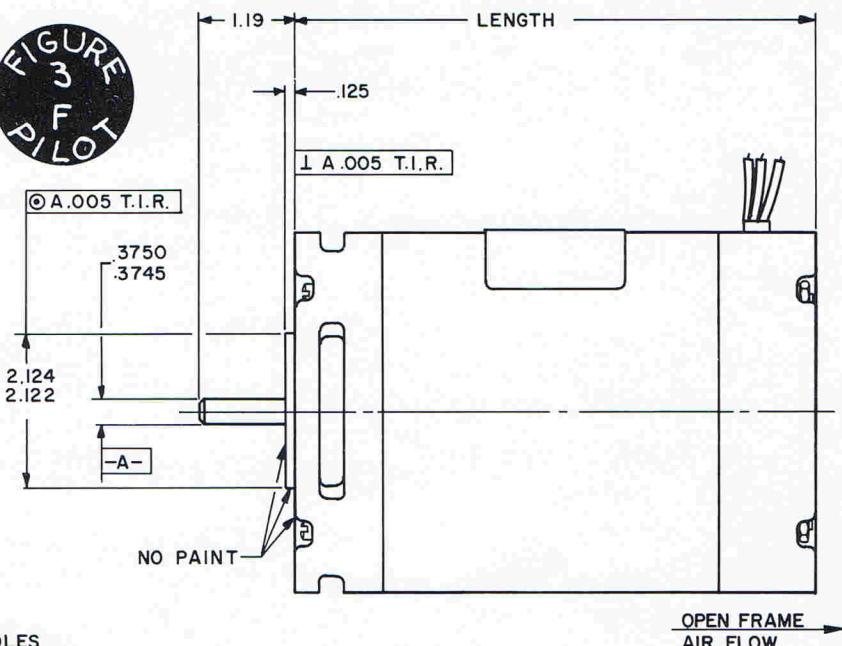


FIGURE  
3  
PILOT



FRAME	LENGTH
GFRN	5.81
GLFRN	6.81
GLLFRN	8.38
GMRN	5.88
GLMRN	6.88
GLLMRN	8.44

TOLERANCES

.XX ± .03  
.XXX ± .005

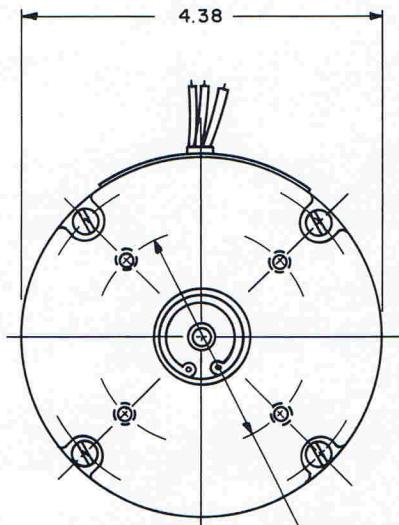
FIGURE  
4  
M  
FACE

NOTE

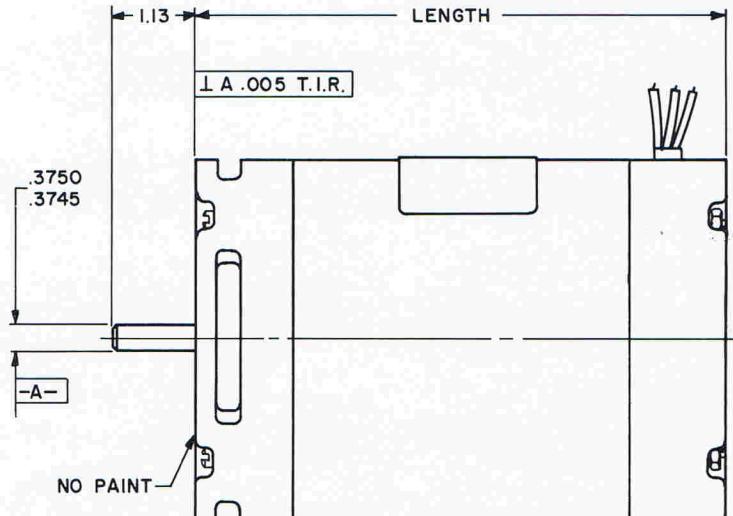
- 1.-ALUMINUM FRAME
- 2-STAINLESS STEEL SHAFT
- 3-BALL BEARING CONSTRUCTION
- 4-MOTOR LEADS 12" LONG
- 5-FINISH-MOTTLETONE BLUE
- 6-SHAFT RUNOUT, .001 T.I.R.

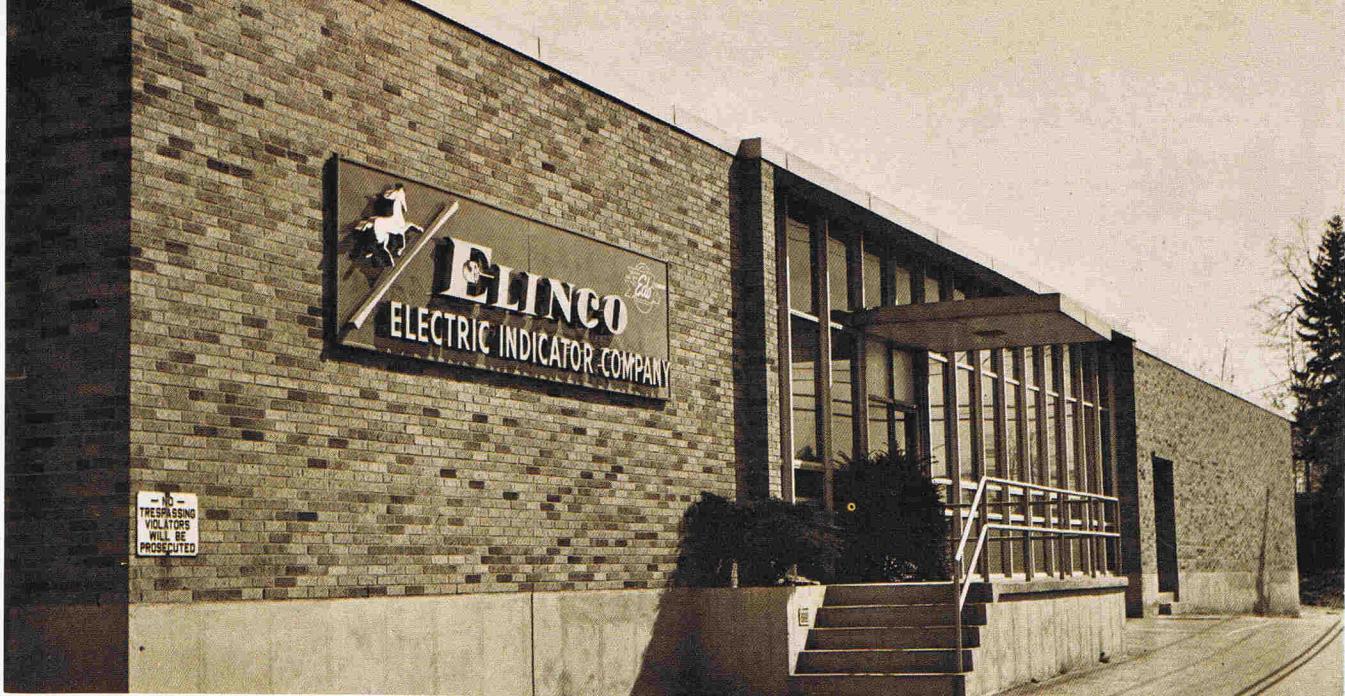
GMRN-GLMRN-GLLMRN

FACE MOUNTING, NO PILOT



2.625, 4 HOLES  
1/4-28, 90° APART  
.38 SCREW DEPTH





## AVAILABLE ELINCO ENGINEERING

ELINCO's Engineering Staff maintains a constant development program which, during the past year alone, developed in excess of a hundred new units to meet difficult commercial and military specifications.

The ELINCO catalogues referred to below contain complete electrical characteristics and physical specifications on hundreds of representative motors and generators:

### A.C. AND D.C. GENERATORS CATALOGUE EI-1

More than 150 representative A.C. and D.C. Generators of the following types:

- A.C. Permanent Magnet Generators
- A.C. Sine Wave Generators
- D.C. Dual Field Generators
- D.C. Permanent Magnet Generators (Tachometers)
- D.C. Speed-Squared Generators
- D.C. Wound Field Generators

### A.C. AND D.C. COMMUTATOR MOTORS

#### CATALOGUE EI-2

More than 200 representative Commutator Motors of the following types:

- A.C. and D.C. Universal Motors
- A.C. and D.C. Split Field-Universal Motors
- D.C. Governor Motors
- D.C. Permanent Magnet Motors
- D.C. Series Motors
- D.C. Split Field Series Motors
- D.C. Separately Excited Shunt Motors
- D.C. Shunt Motors
- D.C. Split Field Shunt Motors

### A.C. INDUCTION AND A.C. TORQUE MOTORS CATALOGUE EI-3

Approximately 100 representative Induction Motors from 15 to 400 cycles, available in one, two or three phase, single or dual speeds, single or dual voltages. Data is included on single phase A.C. Induction Brake Motors.

Also included is complete data on approximately 50 Torque Motors for continuous or intermittent duty, single or multi-phase, 60 cycle or odd frequency, and 115 or odd voltage.

### A.C. SELF-SYNCHRONOUS MOTORS CATALOGUE EI-5

More than two dozen representative motors of the following types:

- A.C. Differential Motors
- A.C. Phase Shifting Rotary Transformers
- A.C. One and Three Phase Rotating Transformers
- A.C. Rotating Self-Synchronous Motors

### A.C. AND D.C. SERVO COMPONENTS CATALOGUE EI-6

Nearly 100 representative Motors and Generators of the following types:

- A.C. Low Inertia Induction Servo Motors
- A.C. Induction Generators
- A.C. Motor-Driven Induction Generators
- A.C. Motor-Generator Sets
- D.C. Motor-Generator Sets

ELINCO's Engineering Staff, with over 40 years experience in the specialized field of sub-fractional electrical rotary equipment, is available to tackle the toughest problems of heat, humidity, shock, vibration, torque, acceleration, weight, mounting and special design. Fast delivery on proto-type units — send your complete electrical and mechanical requirements to: